

On the stability of the invariant probability measures of McKean–Vlasov equations

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Abstract. We study the long-time behavior of some McKean–Vlasov stochastic differential equations used to model the evolution of large populations of interacting agents. We give conditions ensuring the local stability of an invariant probability measure. Lions derivatives are used in a novel way to obtain our stability criteria. We obtain results for non-local McKean–Vlasov equations on $\mathbb{R}^d$ and for McKean–Vlasov equations on the torus where the interaction kernel is given by a convolution. On $\mathbb{R}^d$, we prove that the location of the roots of an analytic function determines the stability. On the torus, our stability criterion involves the Fourier coefficients of the interaction kernel. In both cases, we prove the convergence in the Wasserstein metric W_1 with an exponential rate of convergence.

Résumé. On étudie le comportement en temps long d'équations non-linéaires au sens de McKean–Vlasov. Ces équations sont utilisées pour modéliser les comportements de grandes populations d'agents en interaction. On donne des critères garantissant la stabilité locale d'une mesure de probabilité invariante. Pour ce faire, on utilise de manière novatrice les dérivées de Lions. On obtient des résultats pour des équations de McKean–Vlasov non locales sur $\mathbb{R}^d$, ainsi que pour des équations de McKean–Vlasov sur le tore pour lesquelles le noyau d'interaction est donné par une convolution. Sur $\mathbb{R}^d$, on montre que la stabilité est déterminée par l'emplacement des zéros d'une fonction holomorphe. Sur le tore, notre critère de stabilité fait intervenir les coefficients de Fourier du noyau d'interaction. Dans les deux cas, on montre la convergence vers la mesure de probabilité invariante à vitesse exponentielle pour la métrique de Wasserstein W_1 .

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1. Introduction

We are interested in the long-time behavior of the solutions of a class of McKean–Vlasov stochastic differential equations (SDE) of the form:

$$(1) \quad \begin{aligned} dX_t^v &= \mathcal{V}(X_t^v, \mu_t) dt + \sigma dB_t, \\ \mu_t &= \text{Law}(X_t^v), \quad \mu_0 = \nu. \end{aligned}$$

In this equation, $(B_t)_{t \geq 0}$ is a standard $\mathbb{R}^d$ -valued Brownian motion, σ is a deterministic matrix, and ν is the law of the initial condition X_0^v , assumed to be independent of $(B_t)_{t \geq 0}$. McKean–Vlasov equations appear naturally as the limit $N \rightarrow \infty$ of the following particle system $(X_t^{i,N})_{t \geq 0}$, solution of

$$(2) \quad dX_t^{i,N} = \mathcal{V}(X_t^{i,N}, \mu_t^{i,N}) dt + \sigma dB_t^{i,N}, \quad 1 \leq i \leq N,$$

where $\mu_t^{i,N}$ is the empirical measure $\mu_t^{i,N} = \frac{1}{N} \sum_{j=1}^N \delta_{X_t^{j,N}}$ and $(B_t^{i,N})_{t \geq 0}$ are N independent standard Brownian motions. We refer to [45] for an introduction to this topic.

Such particle systems and their mean-field counterparts are used in a wide range of applications such as plasma physics [22,32], fluid mechanics [25], astrophysics (particles are stars or galaxies [51]), bio-sciences (to understand the

collective behavior of animals [8]), neuroscience (to model assemblies of neurons, such as integrate and fire neurons [20, 26] or FitzHugh–Nagumo neurons [39]), opinion dynamics [18] and economics [10].

In these applications, one important question concerns the long-time behavior of the solutions. As such, the ergodic properties of McKean–Vlasov equations (1) have been studied in many different contexts and approaches.

Two families of assumptions are known to ensure that (1) admits a unique, globally attractive invariant probability measure. The first type of assumption deals with kernels given by $\mathcal{V}(x, \mu) = -\nabla V(x) - \nabla W * \mu(x)$, where V, W have suitable convexity properties. The first results in this direction were obtained in [3, 4] in dimension one. In larger dimensions, [41, 50] proved the convergence uniformly in time of a suitable particle system towards the mean-field equation. As such, they obtained the ergodicity of the McKean–Vlasov equation from the ergodicity of the particle system. These uniformly in time propagation of chaos arguments have been used wisely; see for instance [19, 31] for recent results in this direction. These results have also been obtained by using functional inequalities [5, 12]: the idea is to define a measure-valued functional (known as the entropy or free energy), which only decreases along the trajectories of the solution of (1).

The second kind of assumption involves weak enough interactions. When the dependence of $\mathcal{V}$ with respect to the measure is sufficiently weak, one expects global stability because this situation can be seen as a perturbation of the case without interactions. As such, it is possible to extend techniques from ergodic Markov processes to the case of weak interactions. This includes, for instance, coupling techniques [1, 9, 23, 24, 27] or Picard iterations in suitable spaces [16].

It is also well-known that, in general, such global stability results cannot hold because (1) may have multiple invariant probability measures and periodic solutions [34, 43, 49]. These examples motivate the current question of the paper, namely the study of the local stability of a given invariant probability measure of (1). That is, being given ν_∞ an invariant probability measure of (1), we address the following question:

Is there exist an open neighborhood of ν_∞ such that for all initial conditions ν within this neighborhood, the law of X_t^ν converges to ν_∞ , as t goes to infinity? If so, for which metric does the convergence hold, and what is the rate of convergence?

Such local stability results can be obtained via partial differential equation (PDE) techniques, using that the marginals of the non-linear process solve a non-linear PDE (the Fokker–Planck equation). The strategy is to linearize the non-linear PDE around ν_∞ , to study the existence of a spectral gap for the linear equation in appropriate Banach spaces, and to use perturbation techniques to obtain the convergence for the non-linear PDE. We refer to [33, 40] for an overview of these techniques. When the non-linear PDE admits a gradient flow structure, it is also possible to study the local stability of an invariant probability measure using functional inequalities; see [11, 47, 48]. In [47], the author study the local stability of an invariant probability measure in weighted L^2 norm. The result is obtained assuming a spectral condition related to the positivity of the Hessian of the free energy functional, evaluated at the invariant distribution.

Our approach differs from these two methods on several points. We do not rely on the non-linear Fokker–Planck PDE nor need a gradient flow structure. Instead, we use directly the stochastic representation (1). Our strategy is to differentiate the interaction kernel with respect to the initial probability measure, in the neighborhood of ν_∞ . There are several notions of derivation with respect to probability measures (see [10]): we use here the Lions derivatives. We denote by $\mathcal{P}_2(\mathbb{R}^d)$ the set of probability measures on $\mathbb{R}^d$ having a second moment. For all $x \in \mathbb{R}^d$ and $t \geq 0$, we consider the function

$$\mathcal{P}_2(\mathbb{R}^d) \ni \nu \mapsto \mathcal{V}(x, \text{Law}(X_t^\nu)) =: v_t^x(\nu) \in \mathbb{R}^d,$$

where X_t^ν is the solution of (1) starting with law ν at time 0. We prove that under suitable assumptions, this function is Lions differentiable at ν_∞ , meaning that for all $\nu \in \mathcal{P}_2(\mathbb{R}^d)$, we have

$$\mathcal{V}(x, \text{Law}(X_t^\nu)) = \mathcal{V}(x, \nu_\infty) + \mathbb{E} \partial_\nu v_t^x(\nu_\infty)(Z_0) \cdot (Z - Z_0) + o((\mathbb{E}|Z - Z_0|^2)^{1/2}).$$

In this equation, Z, Z_0 are any random variables defined on the same probability space, with laws equal to ν and ν_∞ . We write $\mathbb{E}(Z - Z_0|Z_0) = h(Z_0)$, where h is a deterministic function from $\mathbb{R}^d$ to $\mathbb{R}^d$. As such, the function h encodes the correlations between the initial conditions Z and Z_0 . It follows from the Cauchy–Schwarz inequality that $\mathbb{E}|h(Z_0)|^2 \leq \mathbb{E}|Z - Z_0|^2 < \infty$. Therefore, $h \in L^2(\nu_\infty)$. We define the linear operator $\Omega_t : L^2(\nu_\infty) \rightarrow L^2(\nu_\infty)$ by

$$\Omega_t(h) := x \mapsto \mathbb{E} \partial_\nu v_t^x(\nu_\infty)(Z_0) \cdot h(Z_0).$$

The fact that $\Omega_t(h) \in L^2(\nu_\infty)$ for all $h \in L^2(\nu_\infty)$ is not granted apriori and will follow from our assumptions on the function $\mathcal{V}$. So we have (recall that $\nu = \text{Law}(Z)$ and $\mathbb{E}(Z - Z_0|Z_0) = h(Z_0)$)

$$\mathcal{V}(x, \text{Law}(X_t^\nu)) = \mathcal{V}(x, \nu_\infty) + \Omega_t(h)(x) + o((\mathbb{E}|Z - Z_0|^2)^{1/2}).$$

Our spectral conditions under which we prove that ν_∞ is locally stable can be stated in terms of the decay of the function $t \mapsto \Omega_t$, as t goes to infinity. We show that the integrability of this function on $\mathbb{R}_+$ implies the stability of ν_∞ . In addition,

the decay of $t \mapsto \Omega_t$ as t goes to infinity gives precisely the rate of convergence of $\text{Law}(X_t^\nu)$ towards ν_∞ , in Wasserstein metrics. Crucial to our analysis, we provide an explicit integral equation to compute this function Ω_t . To do so, we consider the linear process $(Y_t^\nu)_{t \geq 0}$ associated with (1) and ν_∞ , defined as the solution of

$$dY_t^\nu = \mathcal{V}(Y_t^\nu, \nu_\infty) dt + \sigma dB_t,$$

starting from $\text{Law}(Y_0^\nu) = \nu$. We define similarly for $x \in \mathbb{R}^d$ and $t \geq 0$ the function

$$\mathcal{P}_2(\mathbb{R}^d) \ni \nu \mapsto u_t^x(\nu) := \mathcal{V}(x, \text{Law}(Y_t^\nu)).$$

Under non-restrictive assumptions, u_t^x is Lions differentiable at ν_∞ , and we can define

$$\forall h \in L^2(\nu_\infty), \quad \Theta_t(h) := x \mapsto \mathbb{E} \partial_\nu u_t^x(\nu_\infty)(Z_0) \cdot h(Z_0).$$

We prove the following key relation between Θ_t and Ω_t

$$\forall t \geq 0, \quad \Omega_t(h) = \Theta_t(h) + \int_0^t \Theta_{t-s}(\Omega_s(h)) ds.$$

That is, Ω is a solution of a Volterra integral equation whose kernel is given by Θ : in the language of integral equations, Ω is the resolvent of Θ . This relation is helpful because it is easier to get estimates on u_t^x , which involves a linear Markov process, rather than getting estimates on ν_t^x , which involves the solution of the McKean–Vlasov equation (1). In particular, this relation allows to deduce the decay properties of Ω from properties of Θ , using Laplace transform. We obtain our stability results for the Wasserstein W_1 metric.

The contributions of this work are the following. First, in Section 2, we consider dynamics of the form $\mathcal{V}(x, \mu) = b(x) + \int_{\mathbb{R}^d} F(x, y) \mu(dy)$, for some smooth functions $b: \mathbb{R}^d \rightarrow \mathbb{R}^d$ and $F: \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}^d$. The function b is assumed to be confining. Our main result, Theorem 2.5, states that the stability of an invariant probability measure is determined by the location of the roots of an explicit analytic function associated with the dynamics. Stability holds when all the roots lie on the left half-plane, and we prove convergence in Wasserstein metric W_1 with an exponential rate. Our result shows that the stability is completely determined by a discrete set, this set being given by the zeros of an analytic function associated to the underlying Markov process. Note that we do not require any structural assumption on b and F : in particular, we do not require any convexity assumption on the coefficients. Our stability criterion is analogous to the Jacobian stability criterion for ODE, for which the location of the zeros of the characteristic polynomial determines the stability.

Second, in Section 3, we consider a McKean–Vlasov equation on the torus $\mathbb{T}^d := (\mathbb{R}/(2\pi\mathbb{Z}))^d$, with an interaction kernel given by a convolution: $\mathcal{V}(x, \mu) = -\int_{\mathbb{T}^d} \nabla W(x - y) \mu(dy)$, where W is a smooth function from $\mathbb{T}^d$ to $\mathbb{R}$. We assume that $\sigma = \sqrt{2\beta^{-1}} I_d$ for some $\beta > 0$, where I_d is the identity matrix. This setting covers many interesting models; see [11]. We study the stability of the uniform probability measure $U(dx) := \frac{dx}{(2\pi)^d}$. Our second main result, Theorem 3.2, states that when $\inf_{n \in \mathbb{Z}^d \setminus \{0\}} |n|^2(\beta + \tilde{W}(n)) > 0$, $\tilde{W}(n)$ being the n -th Fourier coefficient of W , then U is locally stable for the W_1 metric. Our result complements the results of [11], for which static bifurcations are studied: in particular, we exhibit the same critical parameter. In both parts, we use the strategy described above, using Lions derivatives and probabilistic tools. The criteria we obtain are optimal: violations of the criteria occur strictly at bifurcation points.

The strategy presented in this work also applies to mean-field models of noisy integrate-and-fire neurons: in [15], we study the stability of the stationary solutions of such a mean-field model of noisy neurons by applying the methodology developed here. In addition, periodic solutions via Hopf bifurcations are studied in [17]. For the sake of clarity, we restrict here ourselves to a diffusive setting.

Finally, we mention an important open problem concerning the long-time behavior of the particle system (2). On the one hand, general conditions are known to ensure that the particle system is ergodic. On the other hand, numerical studies show that this particle system can have metastable behavior in the sense that the convergence of the empirical measure μ_t^N towards its invariant state can be very slow when N is large. The locally stable invariant probability measures of the non-linear equation (1) are good candidates to be metastable states of the particle system (2). Characterizing those metastable states in quantitative terms is a challenging mathematical question. Recent partial results have been obtained in this direction [2, 7, 14, 21, 37], and we hope to progress on this question in future works.

2. McKean–Vlasov equations on $\mathbb{R}^d$

2.1. Main result

Let $\mathcal{P}_1(\mathbb{R}^d)$ be the space of probability measures on $\mathbb{R}^d$ with a finite first moment. We consider the following McKean–Vlasov equation on $\mathbb{R}^d$:

$$(3) \quad dX_t^\nu = b(X_t^\nu) dt + \int_{\mathbb{R}^d} F(X_t^\nu, y) \mu_t(dy) dt + \sigma dB_t \quad \text{with } \mu_t = \text{Law}(X_t^\nu).$$

The initial condition X_0^ν has law $\nu \in \mathcal{P}_1(\mathbb{R}^d)$. Here, $(B_t)_{t \geq 0}$ is a d -dimensional standard Brownian motion, $\sigma \in M_d(\mathbb{R})$ is a constant $d \times d$ matrix with $\det \sigma > 0$.

Assumption 2.1. The functions $b : \mathbb{R}^d \rightarrow \mathbb{R}^d$ and $F : \mathbb{R}^{2d} \rightarrow \mathbb{R}^d$ are C^2 , b is globally Lipschitz, and the derivatives of F are bounded (b and F are not assumed to be bounded themselves):

$$\forall i, j \in \{1, \dots, d\}^2, \quad \|\partial_{x_i} F\|_\infty + \|\partial_{x_i, x_j}^2 F\|_\infty < \infty.$$

This ensures in particular that (3) has a unique path-wise solution. Let $\nu_\infty \in \mathcal{P}_1(\mathbb{R}^d)$ be an invariant probability measure of (3), that is:

$$\forall t \geq 0, \quad \text{Law}(X_t^{\nu_\infty}) = \nu_\infty.$$

Denote by $\alpha(x)$ the interaction term under ν_∞ :

$$(4) \quad \forall x \in \mathbb{R}^d, \quad \alpha(x) := \int_{\mathbb{R}^d} F(x, y) \nu_\infty(dy).$$

Each invariant probability measure of (3) is characterized by its associated function α , and we sometimes denote by ν_∞^α such invariant probability measure to emphasize the dependence on α . We assume:

Assumption 2.2. There exists $\beta > 0$ and $R \geq 0$ such that

$$\forall x, x' \in \mathbb{R}^d, \quad |x - x'| \geq R \implies (x - x') \cdot [(b + \alpha)(x) - (b + \alpha)(x')] \leq -\beta |x - x'|^2.$$

Remark 2.3. In particular, this is satisfied provided that F is bounded (or independent of x) and there exists $\beta > 0$ and $R \geq 0$ such that:

$$|x - x'| \geq R \implies (x - x') \cdot (b(x) - b(x')) \leq -\beta |x - x'|^2.$$

Let $(Y_t^\alpha)_{t \geq 0}$ the solution of the linear SDE

$$(5) \quad dY_t^\alpha = b(Y_t^\alpha) dt + \alpha(Y_t^\alpha) dt + \sigma dB_t.$$

Note that $\nu_\infty = \nu_\infty^\alpha$ is also an invariant probability measure of this linear SDE. In addition, a result of Eberle [23] (see (9) below) ensures that ν_∞ is the unique invariant probability measure of (5).

Consider $\mathcal{H} := L^2(\nu_\infty)$ the Hilbert space of measurable functions $h : \mathbb{R}^d \rightarrow \mathbb{R}^d$ satisfying:

$$\|h\|_{\mathcal{H}}^2 := \int |h(y)|^2 \nu_\infty(dy) < \infty.$$

We denote by $\mathcal{L}(\mathcal{H})$ the space of bounded linear operators from $\mathcal{H}$ to itself. Key to our analysis is the following family of bounded linear operators $\Theta_t \in \mathcal{L}(\mathcal{H})$, $t \geq 0$:

$$(6) \quad \forall h \in \mathcal{H}, \quad \Theta_t(h)(x) := \int_{\mathbb{R}^d} \nabla_y \mathbb{E}_y F(x, Y_t^\alpha) \cdot h(y) \nu_\infty^\alpha(dy).$$

The notation $\mathbb{E}_y F(x, Y_t^\alpha)$ means that the initial condition of (Y_t^α) is set to be $y \in \mathbb{R}^d$ (that is $Y_0^\alpha = y$). In addition, $\nabla_y \mathbb{E}_y F(x, Y_t^\alpha)$ is the Jacobian matrix of $y \mapsto \mathbb{E}_y F(x, Y_t^\alpha)$. The result of Eberle [23] (see (10) below) implies that there exists $\kappa_* > 0$ and $C > 0$ such that

$$(7) \quad \forall h \in \mathcal{H}, \quad \|\Theta_t(h)\|_\infty \leq C e^{-\kappa_* t} \|h\|_{\mathcal{H}}.$$

Denote by $I \in \mathcal{L}(\mathcal{H})$ the identity operator. Let $D = \{z \in \mathbb{C}, \Re(z) > -\kappa_*\}$. For all $z \in D$, consider the Laplace transform of Θ_t :

$$\hat{\Theta}(z) = \int_0^\infty e^{-zt} \Theta_t \, dt.$$

We recall some properties of this operator-valued function.

Proposition 2.4. *We have:*

1. For all $z \in D$, $\hat{\Theta}(z) \in \mathcal{L}(\mathcal{H})$ is an Hilbert–Schmidt operator. In particular, $\hat{\Theta}(z)$ is a compact operator.
2. $D \ni z \mapsto \hat{\Theta}(z)$ is an analytic operator-valued function, and $(I - \hat{\Theta}(z))^{-1}$ exists for all $z \in D \setminus S$, where S is a discrete subset of D . In addition, $(I - \hat{\Theta}(z))^{-1}$ is meromorphic in D , holomorphic in $D \setminus S$.
3. The function $D \ni z \mapsto \det(I - \hat{\Theta}(z)) \in \mathbb{C}$ is analytic, where $\det$ is the regularized Fredholm determinant. In addition, $I - \hat{\Theta}(z)$ is invertible if and only if $\det(I - \hat{\Theta}(z)) \neq 0$.

Proof. By Fubini, we have

$$\hat{\Theta}(z)(h) = x \mapsto \int_{\mathbb{R}^d} K_z(x, y) h(y) v_\infty(dy),$$

where $K_z(x, y) := \int_0^\infty e^{-zt} \nabla_y \mathbb{E}_y F(x, Y_t^\alpha) \, dt$. Using (10), it holds that $\sup_{x, y \in \mathbb{R}^d} |K_z(x, y)| < \infty$ for all $z \in D$. Therefore, $K_z(\cdot, \cdot) \in L^2(\mathbb{R}^d \times \mathbb{R}^d, v_\infty \otimes v_\infty)$ and so Theorem VI.23 in [42] applies and gives the first point. For $\Re(z)$ large enough, it holds that $\|\hat{\Theta}(z)\|_{\mathcal{H}} < 1$. Therefore, $I - \hat{\Theta}(z)$ is invertible provided that $\Re(z)$ is large enough, the inverse is given by its Neumann series. So the second point follows from the analytic Fredholm theorem, see Theorem VI.14 in [42]. Finally, the third point is a fundamental result of the theory of Fredholm determinants for Hilbert–Schmidt operators, see for instance [44]. $\square$

Our main result is

Theorem 2.5. *Consider v_∞ an invariant probability measure of (3) and let α be given by (4). Assume that Assumptions 2.1 and 2.2 hold. Define the “abscissa” of the rightmost zeros of $\det(I - \hat{\Theta}(z))$:*

$$(8) \quad -\lambda' := \sup\{\Re(z) \mid z \in D, \det(I - \hat{\Theta}(z)) = 0\}.$$

Assume that $\lambda' > 0$. Then v_∞ is locally stable: there exists $C, \epsilon > 0$ and $\lambda \in (0, \lambda')$ such that for all $v \in \mathcal{P}_1(\mathbb{R}^d)$ with $W_1(v, v_\infty) < \epsilon$, it holds that

$$\forall t \geq 0, \quad W_1(\text{Law}(X_t^\nu), v_\infty) \leq C W_1(v, v_\infty) e^{-\lambda t}.$$

2.2. Remarks and examples

We now give explanations on Theorem 2.5, in particular on the spectral assumption involving (8). From now on, the constants may vary from one line to the other.

Gradients bounds

We denote by (Y_t^{α, δ_x}) the solution of (5) with initial condition $Y_0^{\alpha, \delta_x} = x$. Under assumptions 2.2, Theorem 1 in [23] applies: there exists $\kappa_* > 0$ and $C_* > 1$ such that for all $x, y \in \mathbb{R}^d$ and all $t \geq 0$,

$$(9) \quad W_1(\text{Law}(Y_t^{\alpha, \delta_x}), \text{Law}(Y_t^{\alpha, \delta_y})) \leq C_* e^{-\kappa_* t} |x - y|.$$

We deduce from this inequality the following gradient bound. For all $f \in C^1(\mathbb{R}^d)$:

$$(10) \quad \forall y \in \mathbb{R}^d, \quad |\nabla_y \mathbb{E}_y f(Y_t^\alpha)| \leq C_* \|\nabla f\|_\infty e^{-\kappa_* t}.$$

In particular, by choosing $f = F(x, \cdot)$, we obtain the estimate (7). Note that it is possible to get gradient bounds similar to (10) under less restrictive assumptions on b and σ ; see [46].

On the spectral condition

We consider the following bounded linear operator $\Omega_t \in \mathcal{L}(\mathcal{H})$ by taking the Neumann series:

$$(11) \quad \forall h \in \mathcal{H}, \quad \Omega_t(h) := \sum_{i \geq 1} \Theta_t^{\otimes i}(h),$$

where the linear operators $\Theta_t^{\otimes(i)}$ are defined recursively by

$$\forall t \geq 0, \quad \Theta_t^{\otimes(i+1)}(h) = \int_0^t \Theta_{t-s}(\Theta_s^{\otimes i}(h)) \, ds, \quad \text{and} \quad \Theta_t^{\otimes 1}(h) = \Theta_t(h).$$

The series (11) converges uniformly on any compact $[0, T]$ for $T > 0$. The operators Ω_t and Θ_t satisfy the following Volterra integral equation:

$$(12) \quad \begin{aligned} \forall h \in \mathcal{H}, \quad \Omega_t(h) &= \Theta_t(h) + \int_0^t \Theta_{t-s}(\Omega_s(h)) \, ds \\ &= \Theta_t(h) + \int_0^t \Omega_{t-s}(\Theta_s(h)) \, ds. \end{aligned}$$

We denote by $\|\Omega_t\|_{\mathcal{L}(\mathcal{H})}$ the operator norm of Ω_t :

$$\|\Omega_t\|_{\mathcal{L}(\mathcal{H})} := \sup_{\|h\|_{\mathcal{H}} \leq 1} \|\Omega_t(h)\|_{\mathcal{H}}.$$

Then the spectral condition $\lambda' > 0$ is equivalent to the exponential decay of $t \mapsto \|\Omega_t\|_{\mathcal{L}(\mathcal{H})}$:

Proposition 2.6. *The two following statements are equivalent*

1. $\lambda' > 0$, where λ' is given by (8).
2. $\exists \lambda > 0$ such that $\sup_{t \geq 0} e^{\lambda t} \|\Omega_t\|_{\mathcal{L}(\mathcal{H})} < \infty$.

Proof. We first show that (b) implies (a): by assumption, there exists $\lambda \in (0, \kappa_*)$ such that $z \mapsto \hat{\Omega}(z)$ is an analytic operator-valued function on $\Re(z) > -\lambda$. In view of (12), we have for $\Re(z) > -\lambda$, $\hat{\Omega}(z) = \hat{\Theta}(z) + \hat{\Theta}(z) \cdot \hat{\Omega}(z) = \hat{\Theta}(z) + \hat{\Omega}(z) \cdot \hat{\Theta}(z)$, and so

$$I = (I + \hat{\Omega}(z))(I - \hat{\Theta}(z)) = (I - \hat{\Theta}(z))(I + \hat{\Omega}(z)).$$

Therefore, $I - \hat{\Theta}(z)$ is invertible for all $\Re(z) > -\lambda$, and consequently $\lambda' \geq \lambda > 0$.

We then show that (a) implies (b): this follows from a Paley–Wiener theorem. Let $\lambda \in (0, \lambda')$ and define $K_t := e^{\lambda t} \Theta_t$ and $R_t := e^{\lambda t} \Omega_t$. It holds that $K \in L^1(\mathbb{R}_+; \mathcal{L}(\mathcal{H}))$ (because $\lambda < \kappa_*$) and $I - \hat{K}(z)$ is invertible for all $\Re(z) \geq 0$ (because $\lambda < \lambda'$). Therefore, by [30, Ch. 2, Th. 4.1],¹ it holds that $R \in L^1(\mathbb{R}_+; \mathcal{L}(\mathcal{H}))$. Using the estimate (7) and (12), we find that

$$\begin{aligned} \|\Omega_t(h)\|_{\infty} &\leq C e^{-\kappa_* t} \|h\|_{\mathcal{H}} + C \int_0^t e^{-\kappa_* s} \|\Omega_{t-s}\|_{\mathcal{L}(\mathcal{H})} \|h\|_{\mathcal{H}} \, ds \\ &\leq C \|h\|_{\mathcal{H}} \left(e^{-\kappa_* t} + e^{-\lambda t} \int_0^t e^{\lambda(t-s)} \|\Omega_{t-s}\|_{\mathcal{L}(\mathcal{H})} \, ds \right) \\ &\leq C \|h\|_{\mathcal{H}} \left(1 + \int_0^\infty \|R_s\|_{\mathcal{L}(\mathcal{H})} \, ds \right) e^{-\lambda t}. \end{aligned}$$

This shows that $\sup_{t \geq 0} e^{\lambda t} \|\Omega_t\|_{\mathcal{L}(\mathcal{H})} < \infty$. This ends the proof. □

¹The result in [30] is stated and proved for matrix valued operators. The extension to Hilbert–Schmidt operators is straightforward by the exact same arguments.

The spectral condition is necessary

Let $h \in \mathcal{H}$ be fixed and let Z_0 be a random variable of law ν_∞ . For $\epsilon \in \mathbb{R}$, let $\nu_\epsilon := \text{Law}(Z_0 + \epsilon h(Z_0))$. We will see that the operator Ω_t admits the following probabilistic representation (see Remark 2.23 below):

$$(13) \quad \forall t \geq 0, \quad \Omega_t(h)(x) = \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \int_{\mathbb{R}^d} F(x, y) (\text{Law}(X_t^{\nu_\epsilon}) - \nu_\infty)(dy), \quad x \in \mathbb{R}^d,$$

where $(X_t^{\nu_\epsilon})$ is the solution of the McKean–Vlasov equation (3) starting with law ν_ϵ . We have by the Cauchy–Schwarz inequality

$$W_1(\nu_\epsilon, \nu_\infty) \leq \epsilon \mathbb{E}|h(Z_0)| \leq \epsilon \|h\|_{\mathcal{H}}.$$

Assume that the conclusion of Theorem 2.5 holds. Then there exists $C, \lambda > 0$ such that for all ϵ small enough,

$$W_1(\text{Law}(X_t^{\nu_\epsilon}), \nu_\infty) \leq C \epsilon e^{-\lambda t} \|h\|_{\mathcal{H}}.$$

We deduce that:

$$\forall x \in \mathbb{R}^d, \quad \left| \int_{\mathbb{R}^d} F(x, y) (\text{Law}(X_t^{\nu_\epsilon}) - \nu_\infty)(dy) \right| \leq C \epsilon \|\nabla_y F\|_\infty e^{-\lambda t} \|h\|_{\mathcal{H}}.$$

Therefore,

$$\|\Omega_t(h)\|_\infty \leq C \|\nabla_y F\|_\infty e^{-\lambda t} \|h\|_{\mathcal{H}}.$$

Using Proposition 2.6, we deduce that $\lambda' > 0$, where λ' is given by (8). In other words, the spectral condition $\lambda' > 0$ is necessary to have stability in W_1 norm.

Structural stability with convex coefficients

The classical situation where stability is known to hold globally is the following: assume that there exist functions $V, F : \mathbb{R}^d \rightarrow \mathbb{R}$ such that $b(x) = -\nabla V(x)$ and $F(x, y) = -\nabla W(x - y)$. Assume that W is convex and even and that V is strongly convex:

$$(14) \quad \exists \theta > 0, \forall x \in \mathbb{R}^d, \quad W(x) = W(-x), \quad \nabla^2 W(x) \geq 0, \quad \text{and} \quad \nabla^2 V(x) \geq \theta I_d.$$

Then, by [13, Th. 7], it holds that

$$\forall t \geq 0, \forall \nu, \mu \in \mathcal{P}_2(\mathbb{R}^d), \quad W_2(\text{Law}(X_t^\nu), \text{Law}(X_t^\mu)) \leq e^{-\theta t/2} W_2(\nu, \mu).$$

Therefore, these structural conditions ensure that (3) has a unique invariant probability measure, which is globally stable in W_2 norm. We show that our spectral condition is satisfied under these conditions.

Lemma 2.7. *Under the structural assumption (14), it holds that $\lambda' > 0$, λ' given by (8), and so Theorem 2.5 applies.*

Proof. Let ν_∞ be the unique invariant probability measure of (3). Let $h \in \mathcal{H}$, $\epsilon \in \mathbb{R}$ and let $\nu_\epsilon = \mathcal{L}(Z_0 + \epsilon h(Z_0))$, where $\text{Law}(Z_0) = \nu_\infty$. We have

$$\begin{aligned} \left| \int_{\mathbb{R}^d} \nabla W(x - y) (\text{Law}(X_t^{\nu_\epsilon}) - \nu_\infty)(dy) \right| &\leq \|\nabla^2 W\|_\infty W_1(\text{Law}(X_t^{\nu_\epsilon}), \nu_\infty) \\ &\leq \|\nabla^2 W\|_\infty W_2(\text{Law}(X_t^{\nu_\epsilon}), \nu_\infty) \\ &\leq \|\nabla^2 W\|_\infty e^{-\theta t/2} W_2(\nu_\epsilon, \nu_\infty) \\ &\leq C e^{-\theta t/2} \sqrt{\mathbb{E}|\epsilon h(Z_0)|^2} = C |\epsilon| e^{-\theta t/2} \|h\|_{\mathcal{H}}. \end{aligned}$$

Therefore, by (13), we have

$$\forall h \in \mathcal{H}, \quad \|\Omega_t(h)\|_\infty \leq C e^{-\theta t/2} \|h\|_{\mathcal{H}}.$$

So Proposition 2.6 applies and $\lambda' > 0$. □

Case of weak interactions

One way to check that the spectral condition $\lambda' > 0$ holds, λ' given by (8), is to compute the L^1 norm of Θ_t . Recall that $\|\Theta_t\|_{\mathcal{L}(\mathcal{H})} = \sup_{\|h\|_{\mathcal{H}} \leq 1} \|\Theta_t(h)\|_{\mathcal{H}}$.

Lemma 2.8. *Assume that $\int_0^\infty \|\Theta_t\|_{\mathcal{L}(\mathcal{H})} dt < 1$. Then $\lambda' > 0$ and so ν_∞ is locally stable.*

Proof. Recall that by (7), it holds that $\sup_{t \geq 0} e^{\kappa_* t} \|\Theta_t\|_{\mathcal{L}(\mathcal{H})} < \infty$. Therefore, there exists $\delta > 0$ small enough such that

$$\int_0^\infty e^{\delta t} \|\Theta_t\|_{\mathcal{L}(\mathcal{H})} dt < 1.$$

For $\Re(z) \geq -\delta$, it holds that $\|\hat{\Theta}(z)\|_{\mathcal{L}(\mathcal{H})} \leq \int_0^\infty e^{-\Re(z)t} \|\Theta_t\|_{\mathcal{L}(\mathcal{H})} dt < 1$. We deduce that $I - \hat{\Theta}(z)$ is invertible for $\Re(z) \geq -\delta$, with inverse given by $\sum_{k \geq 0} (\hat{\Theta}(z))^k$. So $\lambda' \geq \delta > 0$. $\square$

This assumption is typically satisfied if the non-linear part in (3) is weak enough. Given $M \in M_d(\mathbb{C})$, let $\|M\|_2$ be the spectral norm of the matrix M . We let $[F] := \sup_{x, y \in \mathbb{R}^d} \|\nabla_y F(x, y)\|_2$. Then, from (9), we have $\|\Theta_t\|_{\mathcal{L}(\mathcal{H})} \leq C_*[F]e^{-\kappa_* t}$. Therefore, if $[F] < \kappa_*/C_*$, then $\lambda' > 0$, and so any invariant probability measure of (3) is locally stable.

Case of “separable” interactions

Assume that F is “separable”, in the sense that there exist functions $w_i : \mathbb{R}^d \rightarrow \mathbb{R}^d$ and $f_i : \mathbb{R}^d \rightarrow \mathbb{R}$ such that

$$\forall x, y \in \mathbb{R}^d \times \mathbb{R}^d, \quad F(x, y) = \sum_{i=1}^p f_i(y) w_i(x).$$

Let $\mathcal{H}_0$ be the following subspace of $\mathcal{H}$ of finite dimension

$$\mathcal{H}_0 := \left\{ h \mid h = \sum_{i=1}^p \beta_i w_i, \beta \in \mathbb{R}^p \right\}.$$

For all $h \in \mathcal{H}$ and for all $t \geq 0$, it holds that $\Theta_t(h) \in \mathcal{H}_0$. The restriction of Θ_t to $\mathcal{H}_0$ can be represented by a $p \times p$ matrix, again denoted by Θ_t , and we have

$$\Theta_t^{i,j} = \int_{\mathbb{R}^d} \nabla_y \mathbb{E}_y f_i(Y_t^\alpha) \cdot w_j(y) \nu_\infty(dy), \quad 1 \leq i, j \leq p.$$

In that case, the determinant in Theorem 2.5 is the standard determinant of matrices. This instance already covers a number of interesting examples.

Case with small noise ($\sigma \simeq 0$)

We now discuss the case where the noise σ is small. The case $\sigma \equiv 0$ would require a special treatment and is not included in Theorem 2.5. It is however instructive to see that the criterion involving (8) is equivalent to the classical stability criterion of a deterministic dynamical systems in $\mathbb{R}^d$. When $\sigma \equiv 0$, the invariant measures are of the form δ_{x_*} for some $x_* \in \mathbb{R}^d$. Let $\mathcal{V}(x, y) = b(x) + F(x, y)$. Assume that

$$(15) \quad \exists \kappa > 0, \quad \sup_{t \geq 0} e^{\kappa t} \|e^{t \nabla_x \mathcal{V}(x_*, x_*)}\|_2 < \infty.$$

This condition means that x_* is a stable equilibrium point for the ODE $\dot{y} = \mathcal{V}(y, x_*)$. Indeed, (15) is equivalent to the fact that the Jacobian matrix of the vector field $x \mapsto \mathcal{V}(x, x_*)$ has all its eigenvalues in the left half-plane $\Re(z) < 0$.

Lemma 2.9. *Assume (15) holds and $\sigma \equiv 0$. Then, the criterion $\lambda' > 0$, λ' given by (8), is equivalent to the fact that the Jacobian matrix of the vector field $x \mapsto \mathcal{V}(x, x)$ at the point x_* has all its eigenvalues in the left half-plane $\Re(z) < 0$.*

The proof is given in the Appendix. We now treat the case σ small using a perturbation argument of $\sigma \equiv 0$. Assume that for $\|\sigma\|_2$ small enough, the McKean–Vlasov equation (1) has a unique invariant measure in the neighborhood of δ_{x_*} . That is, we assume that there exists $\rho_0, \sigma_0 > 0$ such that for any $\sigma \in M_d(\mathbb{R})$ with $\det(\sigma) > 0$ and $\|\sigma\|_2 \leq \sigma_0$, it holds that:

$$\text{Card}\{\nu \in \mathcal{P}_1(\mathbb{R}^d) : W_1(\nu, \delta_{x_*}) \leq \rho_0 \text{ and } \nu \text{ is an invariant probability measure of (1)}\} = 1.$$

We denote by ν_∞^σ be this invariant distribution. To emphasize the dependence on σ , until the end of this section, we also denote by Θ_t^σ the operator given by (6) when the SDE (5) has diffusion coefficient σ . Similarly, we denote by Ω_t^σ the operator defined by (11). The precise description of Θ_t^0 and Ω_t^0 is given in the proof of Lemma 2.9. In particular, we have

$$\Theta_t^0(h)(x) = \nabla_y \mathcal{V}(x, x_*) e^{t \nabla_x \mathcal{V}(x_*, x_*)} \cdot h(x_*).$$

Assume that x_* is a stable point for the ODE $\dot{x} = \mathcal{V}(x, x)$. Then, by (15) and Lemma 2.9, it holds that

$$(16) \quad \exists \kappa > 0, \quad \sup_{t \geq 0} e^{\kappa t} [\|\Theta_t^0\|_{\mathcal{L}(\mathcal{H})} + \|\Omega_t^0\|_{\mathcal{L}(\mathcal{H})}] < \infty.$$

Proposition 2.10. *Assume that (16) holds. In addition assume that for all $\epsilon > 0$, there exists $\theta > 0$ such that*

$$(17) \quad \|\sigma\|_2 \leq \theta \implies \sup_{t \geq 0} e^{\kappa t} \|\Theta_t^\sigma - \Theta_t^0\|_{\mathcal{L}(\mathcal{H})} \leq \epsilon.$$

Then there exists $\sigma_0, \lambda > 0$ such that

$$\|\sigma\|_2 \leq \sigma_0, \quad \sup_{t \geq 0} e^{\lambda t} \|\Omega_t^\sigma\|_{\mathcal{L}(\mathcal{H})} < \infty.$$

Therefore Theorem 2.5 applies and ν_∞^σ is locally stable.

This result can be summarize has follows: assuming that x_* is a stable equilibrium for the ODE $\dot{x} = \mathcal{V}(x, x)$, if (17) holds then stability also hold with small noise. Again, the proof is given on the Appendix. Finally, let us comment on how the rate of convergence depends on σ . Under the assumptions of Proposition 2.10, the constant λ' given by (8) is lower bounded by a strictly positive constant independent of $\|\sigma\|_2 \in [0, \sigma_0]$. However, the rate of convergence is W_1 norm still depends on σ : the bottleneck is coming from the constant κ_* of (9), which in general vanishes as the noise goes to zero. In some specific examples, the rate of convergence does not vanish as σ goes to zero. Consider for instance the case where $b(x) + \int_{\mathbb{R}^d} F(x, y) \nu_\infty^\sigma(dy) = -\nabla V^\sigma(x)$ for some function $V^\sigma : \mathbb{R}^d \rightarrow \mathbb{R}$. Assume that V^σ is a uniformly convex function, uniformly in $\sigma \in [0, \sigma_0]$:

$$\exists \sigma_0, \eta_0 > 0 : \forall \sigma \text{ with } \|\sigma\|_2 \leq \sigma_0, \forall x \in \mathbb{R}^d, \quad \nabla^2 V^\sigma(x) \geq \eta_0 I_d,$$

where I_d denoted the identity matrix on $M_d(\mathbb{R})$. Then (9) holds with constants independent of σ . In that case, the rate of convergence in W_1 norm in Theorem 2.5 does not vanish as the noise vanishes.

A simple explicit example

We close this Section with a simple explicit example. Consider for $J \in \mathbb{R}^*$ the following McKean–Vlasov SDE on $\mathbb{R}$:

$$(18) \quad dX_t = -X_t dt + J \mathbb{E} \cos(X_t) dt + \sqrt{2} dB_t.$$

The associated linear process (Y_t^α) is the solution of the Ornstein–Uhlenbeck SDE

$$dY_t^\alpha = -Y_t^\alpha dt + \alpha dt + \sqrt{2} dB_t.$$

This linear process admits a unique invariant probability measure given by $\nu_\infty^\alpha = \mathcal{N}(\alpha, 1)$, such that if G is a standard Gaussian random variable, $\mathbb{E} \cos(Y_t^{\alpha, \nu_\infty^\alpha}) = \mathbb{E} \cos(\alpha + G) = \frac{\cos(\alpha)}{\sqrt{e}}$. We deduce that the invariant probability measures of (18) are $\{\mathcal{N}(\alpha, 1) \mid \alpha \in \mathbb{R}, \frac{\sqrt{e}}{J} \alpha = \cos(\alpha)\}$. Let $\alpha \in \mathbb{R}$ such that $\frac{\sqrt{e}}{J} \alpha = \cos(\alpha)$. We have:

$$\forall t \geq 0, \quad \Theta_t = J \int_{\mathbb{R}} \frac{d}{dy} \mathbb{E}_y \cos(Y_t^\alpha) \nu_\infty^\alpha(dy) = -\frac{J}{\sqrt{e}} e^{-t} \sin(\alpha).$$

So, for $\Re(z) > -1$, $\widehat{\Theta}(z) = -\frac{J}{z+1} e^{-1/2} \sin(\alpha)$ and the equation $\widehat{\Theta}(z) = 1$ has a unique solution $z = -J e^{-1/2} \sin(\alpha) - 1$. This root is strictly negative if and only if $J \sin(\alpha) > -\sqrt{e}$. We deduce by Theorem 2.5 that ν_∞^α is locally stable provided that $J \sin(\alpha) > -\sqrt{e}$. Recall that $\alpha \sqrt{e} = J \cos(\alpha)$. So among all the invariant probability measures of (18), the (locally) stable ones are the $\mathcal{N}(\alpha, 1)$ with

$$\alpha \tan(\alpha) > -1.$$

2.3. Notations

For $x \in \mathbb{R}^d$, we denote by $|x|$ its Euclidean norm. Recall that $\mathcal{H} := L^2(\nu_\infty)$ is the Hilbert space of measurable functions $h : \mathbb{R}^d \rightarrow \mathbb{R}^d$ such that

$$\|h\|_{\mathcal{H}}^2 := \int |h(x)|^2 \nu_\infty(dx) < \infty.$$

We denote by $\mathcal{K} := W^{1,\infty}(\mathbb{R}^d; \mathbb{R}^d)$ the subspace of $\mathcal{H}$ consisting of all bounded and Lipschitz continuous functions $k : \mathbb{R}^d \rightarrow \mathbb{R}^d$. We equip $\mathcal{K}$ with:

$$\forall k \in \mathcal{K}, \quad \|k\|_{\mathcal{K}} := \|k\|_\infty + \|\nabla k\|_\infty.$$

Note that, using Assumptions 2.1 and 2.2, the operators Θ_t and Ω_t , defined by (6) and (12), map $\mathcal{H}$ to $\mathcal{K}$. Given I a closed interval of $\mathbb{R}_+$, we denote by $C(I; \mathcal{K})$ the space of continuous functions from I to $\mathcal{K}$. Let $\alpha : \mathbb{R}^d \rightarrow \mathbb{R}^d$ satisfying (4). Let $k \in C(\mathbb{R}_+; \mathcal{K})$. Consider $Y_t^{\alpha+k, \nu}$ the solution of the following linear non-homogeneous $\mathbb{R}^d$ -valued SDE

$$(19) \quad dY_t^{\alpha+k, \nu} = b(Y_t^{\alpha+k, \nu}) dt + \alpha(Y_t^{\alpha+k, \nu}) dt + k_t(Y_t^{\alpha+k, \nu}) dt + \sigma dB_t,$$

where the initial condition satisfies $\text{Law}(Y_0^{\alpha+k, \nu}) = \nu$. Note that $Y_t^{\alpha+k, \nu}$ is a solution of (3) provided that k satisfies the following closure equation:

$$(20) \quad \forall x \in \mathbb{R}^d, \forall t \geq 0, \quad \alpha(x) + k_t(x) = \mathbb{E}F(x, Y_t^{\alpha+k, \nu}).$$

Finally, for $y \in \mathbb{R}^d$ and g a test function, we write $\mathbb{E}_y g(Y_t^{\alpha+k}) := \mathbb{E}g(Y_t^{\alpha+k, \delta_y})$.

A key ingredient in the proof of Theorem 2.5 is the notion of Lions derivatives. A function $u : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R}$ is Lions differentiable at $\nu_0 \in \mathcal{P}_2(\mathbb{R}^d)$ if there exists a deterministic function $\partial_\nu u(\nu_0) : \mathbb{R}^d \rightarrow \mathbb{R}^d$ such that for every random variables Z_0, H defined on the same probabilistic space $(\Omega, \mathcal{F}, \mathbb{P})$ with $\text{Law}(Z_0) = \nu_0$ and $\mathbb{E}|H|^2 < \infty$, we have for $\nu = \text{Law}(Z_0 + H)$:

$$u(\nu) = u(\nu_0) + \mathbb{E}[\partial_\nu u(\mu_0)(Z_0) \cdot H] + o(\sqrt{\mathbb{E}|H|^2}), \quad \text{as } \mathbb{E}|H|^2 \text{ goes to zero.}$$

We refer to [10] for a detailed presentation of this theory. Let $\psi \in C^1(\mathbb{R}^d)$ with $\|\nabla \psi\|_\infty < \infty$. We recall that the linear functional

$$u(\nu) = \int_{\mathbb{R}^d} \psi(y) \nu(dy)$$

is Lions differentiable at every $\nu_0 \in \mathcal{P}_2(\mathbb{R}^d)$, with a Lions derivative given by

$$\partial_\mu u(\nu_0)(y) = \nabla \psi(y).$$

2.4. An integrated sensibility formula

Let $\alpha : \mathbb{R}^d \rightarrow \mathbb{R}^d$ satisfying (4). The goal of this Section is to prove the following “integrated sensitivity formula”.

Proposition 2.11. *Let $k \in C(\mathbb{R}_+; \mathcal{K})$ and $\nu \in \mathcal{P}_1(\mathbb{R}^d)$. Let $g \in C^2(\mathbb{R}^d)$ with $\|\nabla g\|_\infty + \|\nabla^2 g\|_\infty < \infty$. It holds that for all $t \geq 0$,*

$$\mathbb{E}g(Y_t^{\alpha+k, \nu}) - \mathbb{E}g(Y_t^{\alpha, \nu}) = \int_0^t \int_{\mathbb{R}^d} [\nabla_y \mathbb{E}_y g(Y_{t-\theta}^\alpha) \cdot k_\theta(y)] \text{Law}(Y_\theta^{\alpha+k, \nu})(dy) d\theta.$$

Without loss of generality, we can assume that the initial condition ν belongs to $\mathcal{P}_2(\mathbb{R}^d)$. We define for all $0 \leq \theta \leq t$:

$$\forall \nu \in \mathcal{P}_2(\mathbb{R}^d), \quad u_{t,\theta}^g(\nu) := \mathbb{E}g(Y_{t-\theta}^{\alpha, \nu}).$$

By the Markov property, $u_{t,\theta}^g$ is linear with respect to ν :

$$u_{t,\theta}^g(\nu) = \int_{\mathbb{R}^d} \mathbb{E}_y g(Y_{t-\theta}^\alpha) \nu(dy).$$

By [29, Th. 7.18], the function $y \mapsto \mathbb{E}_y g(Y_{t-\theta}^\alpha)$ is continuously differentiable with a bounded derivative. So $u_{t,\theta}^g$ is Lions differentiable with

$$\partial_v u_{t,\theta}^g(v)(y) = \nabla_y \mathbb{E}_y g(Y_{t-\theta}^\alpha).$$

Therefore, it suffices to prove that

$$\mathbb{E}g(Y_t^{\alpha+k,v}) - \mathbb{E}g(Y_t^{\alpha,v}) = \int_0^t \mathbb{E}[\partial_v u_{t,\theta}^g(\text{Law}(Y_\theta^{\alpha+k,v}))(Y_\theta^{\alpha+k,v}) \cdot k_\theta(Y_\theta^{\alpha+k,v})] d\theta.$$

Given $\theta \geq 0$ and $k \in C(\mathbb{R}_+; \mathcal{K})$, we write for all $u \geq 0$:

$$(21) \quad \forall y \in \mathbb{R}^d, \quad k_u^{[\theta]}(y) := \begin{cases} k_u(y) & \text{if } u \leq \theta \\ 0 & \text{if } u > \theta \end{cases}$$

The proof of Proposition 2.11 is deduced from the following Lemma and from the fundamental theorem of calculus.

Lemma 2.12. *The function $\theta \mapsto \mathbb{E}g(Y_t^{\alpha+k^{[\theta]},v})$ is differentiable for all $\theta \in (0, t)$ and*

$$(22) \quad \frac{d}{d\theta} \mathbb{E}g(Y_t^{\alpha+k^{[\theta]},v}) = \mathbb{E} \partial_v u_{t,\theta}^g(\text{Law}(Y_\theta^{\alpha+k,v}))(Y_\theta^{\alpha+k,v}) \cdot k_\theta(Y_\theta^{\alpha+k,v}).$$

Proof. Fix $\theta \in (0, t)$ and $\delta > 0$ small enough such that $\theta + \delta \in (0, t)$. We write

$$\begin{aligned} Y_\theta &:= Y_\theta^{\alpha+k,v}, & Y_{\theta+\delta}^1 &:= Y_{\theta+\delta}^{\alpha+k^{[\theta]},v}, & Y_{\theta+\delta}^2 &:= Y_{\theta+\delta}^{\alpha+k,v} \\ \mu_\theta &:= \text{Law}(Y_\theta), & \mu_{\theta+\delta}^1 &:= \text{Law}(Y_{\theta+\delta}^1), & \mu_{\theta+\delta}^2 &:= \text{Law}(Y_{\theta+\delta}^2). \end{aligned}$$

The notations are illustrated on Figure 1. We have by the Markov property satisfied by Y at time $\theta + \delta$

$$\mathbb{E}g(Y_t^{\alpha+k^{[\theta+\delta]},v}) - \mathbb{E}g(Y_t^{\alpha+k^{[\theta]},v}) = \mathbb{E}g(Y_{t-(\theta+\delta)}^{\alpha,\mu_{\theta+\delta}^2}) - \mathbb{E}g(Y_{t-(\theta+\delta)}^{\alpha,\mu_{\theta+\delta}^1}).$$

By definition of the Lions derivative at the point $\mu_{\theta+\delta}^1$ we have

$$(23) \quad \mathbb{E}g(Y_{t-(\theta+\delta)}^{\alpha,\mu_{\theta+\delta}^2}) - \mathbb{E}g(Y_{t-(\theta+\delta)}^{\alpha,\mu_{\theta+\delta}^1}) = \mathbb{E} \partial_v u_{t,\theta+\delta}^g(\mu_{\theta+\delta}^1)(Y_{\theta+\delta}^1) \cdot (Y_{\theta+\delta}^2 - Y_{\theta+\delta}^1) + o(\sqrt{\mathbb{E}|Y_{\theta+\delta}^2 - Y_{\theta+\delta}^1|^2}).$$

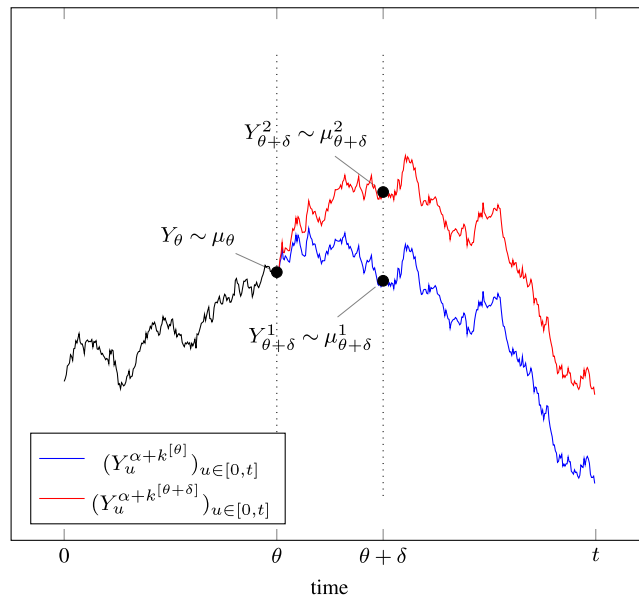


Fig. 1. The two trajectories are driven by the same Brownian motion, with same drift except between times θ and $\theta + \delta$.

By Lemma 2.13 (a) below, it holds that $o(\sqrt{\mathbb{E}|Y_{\theta+\delta}^2 - Y_{\theta+\delta}^1|^2}) = o(\delta)$ as δ goes to zero. We now approximate $Y_{\theta+\delta}^1$ and $Y_{\theta+\delta}^2$ by a one-step Euler scheme:

$$(24) \quad \begin{aligned} Y_{\theta+\delta}^1 &\approx \tilde{Y}_{\theta+\delta}^1 := Y_\theta + \alpha(Y_\theta)\delta + \sigma(W_{\theta+\delta} - W_\theta) \\ Y_{\theta+\delta}^2 &\approx \tilde{Y}_{\theta+\delta}^2 := Y_\theta + \alpha(Y_\theta)\delta + k_\theta(Y_\theta)\delta + \sigma(W_{\theta+\delta} - W_\theta) \end{aligned}$$

Note that $\tilde{Y}_{\theta+\delta}^2 - \tilde{Y}_{\theta+\delta}^1 = k_\theta(Y_\theta)\delta$. These one-step Euler schemes have an error in L^2 norm of size $o(\delta)$ (see Lemma 2.13 (c) below), therefore:

$$\sqrt{\mathbb{E}|Y_{\theta+\delta}^1 - \tilde{Y}_{\theta+\delta}^1|^2} + \sqrt{\mathbb{E}|Y_{\theta+\delta}^2 - \tilde{Y}_{\theta+\delta}^2|^2} = o(\delta),$$

so (23) gives

$$\mathbb{E}g(Y_{t-(\theta+\delta)}^{\alpha, \mu_{\theta+\delta}^2}) - \mathbb{E}g(Y_{t-(\theta+\delta)}^{\alpha, \mu_{\theta+\delta}^1}) = \delta \mathbb{E}[\partial_v u_{t, \theta+\delta}^g(\mu_{\theta+\delta}^1)(Y_{\theta+\delta}^1) \cdot k_\theta(Y_\theta)] + o(\delta).$$

Finally, one has

$$\begin{aligned} &|\mathbb{E}[\partial_v u_{t, \theta+\delta}^g(\mu_{\theta+\delta}^1)(Y_{\theta+\delta}^1) \cdot k_\theta(Y_\theta)] - \mathbb{E}[\partial_v u_{t, \theta}^g(\mu_\theta)(Y_\theta) \cdot k_\theta(Y_\theta)]| \\ &\leq |\mathbb{E}[\partial_v u_{t, \theta+\delta}^g(\mu_{\theta+\delta}^1)(Y_{\theta+\delta}^1) \cdot k_\theta(Y_\theta)] - \mathbb{E}[\partial_v u_{t, \theta+\delta}^g(\mu_\theta)(Y_\theta) \cdot k_\theta(Y_\theta)]| \\ &\quad + |\mathbb{E}[\partial_v u_{t, \theta+\delta}^g(\mu_\theta)(Y_\theta) \cdot k_\theta(Y_\theta)] - \mathbb{E}[\partial_v u_{t, \theta}^g(\mu_\theta)(Y_\theta) \cdot k_\theta(Y_\theta)]| =: A_1 + A_2. \end{aligned}$$

By Lemma 2.14 (a) there exists a constant $C(t)$ such that

$$A_1 \leq C(t) \|k_\theta\|_{\mathcal{K}} \sqrt{\mathbb{E}|Y_{\theta+\delta}^1 - Y_\theta|^2} \stackrel{\text{Lem. 2.13 (b)}}{\leq} C(t) \sqrt{\delta} \sup_{\theta \in [0, t]} \|k_\theta\|_{\mathcal{K}}.$$

Let $\epsilon > 0$ be fixed. Lemma 2.14 (b) yields for δ small enough:

$$A_2 \leq \epsilon \sup_{\theta \in [0, t]} \|k_\theta\|_{\mathcal{K}}.$$

Altogether, we find that

$$\mathbb{E}g(Y_t^{a+k[\theta+\delta], v}) - \mathbb{E}g(Y_t^{a+k[\theta], v}) = \delta \mathbb{E}[\partial_v u_{t, \theta}^g(\mu_\theta)(Y_\theta) \cdot k_\theta(Y_\theta)] + o(\delta).$$

This ends the proof. □

We used the following classical estimates (the constants depend on α and k):

Lemma 2.13. *We have, with the notations introduced in the proof of Lemma 2.12,*

1. *it holds that $\mathbb{E}|Y_{\theta+\delta}^2 - Y_{\theta+\delta}^1|^2 \leq C(t)\delta^2$.*
2. *it holds that $\mathbb{E}|Y_{\theta+\delta}^1 - Y_\theta|^2 \leq C(t)\delta$.*
3. *the Euler scheme (24) satisfies $\mathbb{E}|Y_{\theta+\delta}^1 - \tilde{Y}_{\theta+\delta}^1|^2 + \mathbb{E}|Y_{\theta+\delta}^2 - \tilde{Y}_{\theta+\delta}^2|^2 = o(\delta^2)$, as δ goes to zero.*

We also used the following regularity results on $\partial_v u_{t, s}^g(v)(y) = \nabla_y \mathbb{E}_y g(Y_{t-s}^\alpha)$. The proofs follow easily from the stochastic representation of $y \mapsto \nabla_y \mathbb{E}_y g(Y_{t-s}^\alpha)$: in particular this function has a bounded derivative (because $\|\nabla g\|_\infty + \|\nabla^2 g\|_\infty < \infty$, see [29, Th. 7.18]).

Lemma 2.14. *It holds that:*

1. *there exists a constant $C(t)$ such that any square-integrable variables Z, Z' ,*

$$\sup_{0 \leq s \leq t} \mathbb{E}|\partial_v u_{t, s}^g(\text{Law}(Z))(Z) - \partial_v u_{t, s}^g(\text{Law}(Z'))(Z')|^2 \leq C(t) \mathbb{E}|Z - Z'|^2.$$

2. the function $s \mapsto \partial_\nu u_{t,s}^g(\text{Law}(Z))(Z)$ is continuous: for all $\epsilon > 0$ there exists $\delta > 0$:

$$\forall s, s' \in [0, t], \quad |s - s'| \leq \delta \implies \mathbb{E} \left| \partial_\nu u_{t,s'}^g(\text{Law}(Z))(Z) - \partial_\nu u_{t,s}^g(\text{Law}(Z))(Z) \right|^2 < \epsilon.$$

Remark 2.15. It is also possible to prove Proposition 2.11 without using Lions derivatives. Fix $t > 0$ and define for $s \in (0, t)$

$$(s, y) \mapsto \phi(s, y) := \mathbb{E}_y g(Y_{t-s}^\alpha).$$

Given $k \in C([0, t]; \mathcal{K})$, we denote by

$$\mathcal{L}_\theta^{\alpha+k} \psi := (b + \alpha + k_\theta) \cdot \nabla \psi + \frac{1}{2} \sum_{i,j=1}^d (\sigma \sigma^*)_{i,j} \partial_{x_i} \partial_{x_j} \psi, \quad \theta \in [0, t],$$

the infinitesimal generator associated to $Y^{\alpha+k}$. It holds that $\phi \in C^{1,2}([0, t] \times \mathbb{R}^d)$ with

$$\frac{\partial}{\partial s} \phi(s, y) = -\mathcal{L}_s^\alpha \phi(s, y).$$

So, by Itô's lemma,

$$\begin{aligned} \mathbb{E} \phi(s, Y_s^{\alpha+k, \nu}) &= \mathbb{E} \phi(0, Y_0^{\alpha+k, \nu}) - \int_0^s \mathbb{E} \mathcal{L}_\theta^\alpha \phi(\theta, Y_\theta^{\alpha+k, \nu}) d\theta + \int_0^s \mathbb{E} \mathcal{L}_\theta^{\alpha+k} \phi(\theta, Y_\theta^{\alpha+k, \nu}) d\theta \\ &= \mathbb{E} \phi(0, Y_0^{\alpha+k, \nu}) + \int_0^s \mathbb{E} \nabla_y \phi(\theta, Y_\theta^{\alpha+k, \nu}) \cdot k_\theta(Y_\theta^{\alpha+k, \nu}) d\theta. \end{aligned}$$

We used that $\mathcal{L}_\theta^{\alpha+k} \psi - \mathcal{L}_\theta^\alpha \psi = \nabla \psi \cdot k_\theta$. Using the definition of ϕ , we find:

$$\mathbb{E} \phi(s, Y_s^{\alpha+k, \nu}) = \mathbb{E} g(Y_t^{\alpha, \nu}) + \int_0^s \int_{\mathbb{R}^d} \nabla_y \mathbb{E}_y g(Y_{t-\theta}^\alpha) \cdot k_\theta(y) \mathcal{L}(Y_\theta^{\alpha+k, \nu})(dy) d\theta.$$

Finally, we let s converges to t and find the stated formula.

As a corollary, we obtain the following apriori control of the Wasserstein distance between two solutions of SDE driven by slightly different drifts. Recall that $C_*, \kappa_* > 0$ are given by (9).

Corollary 2.16. For all $t \geq 0$ and $k \in C([0, t]; \mathcal{K})$, it holds that

$$W_1(\text{Law}(Y_t^{\alpha+k, \nu}), \text{Law}(Y_t^{\alpha, \nu})) \leq C \int_0^t e^{-\kappa_*(t-\theta)} \|k_\theta\|_\infty d\theta.$$

Proof. Let $g \in C^2(\mathbb{R}^d)$. Using (10) and Proposition 2.11, we have for $g \in C^2(\mathbb{R}^d)$,

$$|\mathbb{E} g(Y_t^{\alpha+k, \nu}) - \mathbb{E} g(Y_t^{\alpha, \nu})| \leq C_* \|\nabla g\|_\infty \int_0^t e^{-\kappa_*(t-\theta)} \|k_\theta\|_\infty d\theta.$$

This inequality also holds if $g \in C^1(\mathbb{R}^d)$ by a standard approximation argument. □

Note that by choosing $g = F(x, \cdot)$, Proposition 2.11 gives:

$$(25) \quad \mathbb{E} F(x, Y_t^{\alpha+k, \nu}) - \mathbb{E} F(x, Y_t^{\alpha, \nu}) = \int_0^t \int_{\mathbb{R}^d} \nabla_y \mathbb{E}_y F(x, Y_{t-\theta}^\alpha) \cdot k_\theta(y) \text{Law}(Y_\theta^{\alpha+k, \nu})(dy) d\theta.$$

Recall that $\Theta_t(k)$ is defined by (6). When $\nu = \nu_\infty$ and when k is small, we obtain:

$$\mathbb{E} F(x, Y_t^{\alpha+k, \nu_\infty}) - \alpha(x) \approx \int_0^t \int_{\mathbb{R}^d} \nabla_y \mathbb{E}_y F(x, Y_{t-\theta}^\alpha) \cdot k_\theta(y) \nu_\infty(dy) d\theta = \int_0^t \Theta_{t-\theta}(k_\theta)(x) d\theta.$$

This observation is crucially used in the next Section.

2.5. Control of the non-linear interactions

Recall that (X_t^ν) denotes the solution of the McKean–Vlasov equation (3). For all $t \geq 0$ and $\nu \in \mathcal{P}_1(\mathbb{R}^d)$, we define

$$\begin{aligned}\varphi_t^\nu(x) &:= \mathbb{E}F(x, Y_t^{\alpha, \nu}) - \alpha(x), \\ k_t^\nu(x) &:= \mathbb{E}F(x, X_t^\nu) - \alpha(x).\end{aligned}$$

Recall that $\Omega_t(h)$ is defined by (11). In this Section, we prove that:

Proposition 2.17. *For all $T > 0$, there is a constant C_T such that for all $t \in [0, T]$, for all $x \in \mathbb{R}^d$ and for all $\nu \in \mathcal{P}_1(\mathbb{R}^d)$:*

$$\left| k_t^\nu(x) - \varphi_t^\nu(x) - \int_0^t \Omega_{t-s}(\varphi_s^\nu)(x) \, ds \right| \leq C_T (W_1(\nu, \nu_\infty))^2.$$

The first step is to show the following apriori estimate on k_t^ν :

Lemma 2.18. *Let $T > 0$. There exists a constant C_T such that*

$$\forall \nu \in \mathcal{P}_1(\mathbb{R}^d), \quad \sup_{t \in [0, T]} \|k_t^\nu\|_{\mathcal{K}} \leq C_T W_1(\nu, \nu_\infty).$$

In addition, $k^\nu \in C([0, T]; \mathcal{K})$.

Proof. We have

$$k_t^\nu(x) = \int_{\mathbb{R}^d} F(x, y) (\text{Law}(X_t^\nu) - \nu_\infty)(dy).$$

Using Lemma 2.20 below, we deduce that $|k_t^\nu(x)| \leq C_T \|\nabla_y F\|_\infty W_1(\nu, \nu_\infty)$. Similarly,

$$|\nabla k_t^\nu(x)| \leq C_T \|\nabla_{x,y}^2 F\|_\infty W_1(\nu, \nu_\infty).$$

This shows the bound on $\sup_{t \in [0, T]} \|k_t^\nu\|_{\mathcal{K}}$. Moreover,

$$k_t^\nu(x) - k_s^\nu(x) = \int_{\mathbb{R}^d} F(x, y) (\text{Law}(X_t^\nu) - \text{Law}(X_s^\nu))(dy).$$

In addition, for all $T > 0$ and $\nu \in \mathcal{P}_1(\mathbb{R}^d)$, there exists a constant $C(T, \nu)$ such that

$$\forall 0 \leq s \leq t \leq T, \quad W_1(\text{Law}(X_t^\nu), \text{Law}(X_s^\nu)) \leq \mathbb{E}|X_t^\nu - X_s^\nu| \leq C(T, \nu) \sqrt{t-s}.$$

We deduce that $k^\nu \in C([0, T]; \mathcal{H})$. □

Next, using Proposition 2.11, we show that:

Lemma 2.19. *For all $T > 0$, there is a constant C_T such that for all $t \in [0, T]$, for all $x \in \mathbb{R}^d$ and for all $\nu \in \mathcal{P}_1(\mathbb{R}^d)$:*

$$\left| k_t^\nu(x) - \varphi_t^\nu(x) - \int_0^t \Theta_{t-s}(k_s^\nu)(x) \, ds \right| \leq C_T (W_1(\nu, \nu_\infty))^2.$$

Proof. Using the closure equation (20), we have:

$$\begin{aligned}k_t^\nu(x) &= \mathbb{E}F(x, Y_t^{\alpha+k^\nu, \nu}) - \alpha(x) \\ &= \mathbb{E}F(x, Y_t^{\alpha+k^\nu, \nu}) - \mathbb{E}F(x, Y_t^{\alpha, \nu}) + \varphi_t^\nu(x).\end{aligned}$$

We apply Proposition 2.11 and obtain:

$$k_t^\nu(x) - \varphi_t^\nu(x) = \int_0^t \int_{\mathbb{R}^d} \nabla_y \mathbb{E}_y F(x, Y_{t-\theta}^\alpha) \cdot k_\theta^\nu(y) \text{Law}(X_\theta^\nu)(dy) \, d\theta.$$

We used that $\text{Law}(Y_{\theta}^{\alpha+k^v, v}) = \text{Law}(X_{\theta}^v)$. Let

$$G_{t,\theta}^x(y) := \nabla_y \mathbb{E}_y F(x, Y_{t-\theta}^{\alpha}) \cdot k_{\theta}^v(y).$$

We deduce that:

$$k_t^v(x) - \varphi_t^v(x) = \int_0^t \Theta_{t-\theta}(k_s^v)(x) \, ds + R_t(x),$$

where

$$R_t(x) := \int_0^t (\mathbb{E} G_{t,\theta}^x(X_{\theta}^v) - \mathbb{E} G_{t,\theta}^x(X_{\theta}^{v_{\infty}})) \, d\theta.$$

Using Lemma 2.18, we deduce for all $T > 0$, there exists a constant C_T , such that

$$\forall x \in \mathbb{R}^d, \forall 0 \leq \theta \leq t \leq T, \quad \|\nabla G_{t,\theta}^x\|_{\infty} \leq C_T W_1(v, v_{\infty}).$$

Therefore, using Lemma 2.20 below, we deduce that $|R_t(x)| \leq C_T (W_1(v, v_{\infty}))^2$. □

By iterating the estimate of Lemma 2.19, we deduce the proof of Proposition 2.17.

Proof of Proposition 2.17. For $i \in \mathbb{N}$, define:

$$\psi_t^i(x) := \varphi_t^v(x) + \int_0^t \Theta_{t-\theta}(\varphi_{\theta}^v)(x) \, d\theta + \cdots + \int_0^t \Theta_{t-\theta}^{\otimes i}(\varphi_{\theta}^v)(x) \, d\theta.$$

Let D_T a constant such that for all $k \in \mathcal{K}$, $\sup_{t \in [0, T]} \|\Theta_t(k)\|_{\infty} \leq D_T \|k\|_{\infty}$. By induction, we have:

$$\forall t \in [0, T], \quad \|\Theta_t^{\otimes i}(k)\|_{\infty} \leq (D_T)^i \frac{t^{i-1}}{(i-1)!} \|k\|_{\infty}.$$

Let C_T be the constant of Lemma 2.19. By induction, we deduce that:

$$\left\| k_t^v - \psi_t^i - \int_0^t \Theta_{t-\theta}^{\otimes(i+1)}(k_{\theta}^v) \, d\theta \right\|_{\infty} \leq C_T (W_1(v, v_{\infty}))^2 \left(1 + D_T t + \cdots + \frac{(D_T t)^i}{i!} \right).$$

To conclude, it suffices to take the limit $i \rightarrow \infty$: ψ_t^i converges uniformly to $\varphi_t^v + \int_0^t \Omega_{t-\theta}(\varphi_s^v) \, ds$, and $\int_0^t \Theta_{t-\theta}^{\otimes(i+1)}(k_{\theta}^v) \, d\theta$ converges uniformly to zero. This ends the proof. □

We used the following apriori estimate on the solution of (3).

Lemma 2.20. Let $T > 0$. There exists a constant C_T such that for all $\mu_1, \mu_2 \in \mathcal{P}_1(\mathbb{R}^d)$,

$$\forall t \in [0, T], \quad W_1(\text{Law}(X_t^{\mu_1}), \text{Law}(X_t^{\mu_2})) \leq C_T W_1(\mu_1, \mu_2).$$

Proof. Consider $(X_t^{\mu_1}, X_t^{\mu_2})$ the solutions of (3) coupled with the same Brownian motion. The initial conditions $(X_0^{\mu_1}, X_0^{\mu_2})$ are chosen such that $\mathbb{E}|X_0^{\mu_1} - X_0^{\mu_2}| = W_1(\mu_1, \mu_2)$. Let $\mu_t^1 := \text{Law}(X_t^{\mu_1})$ and $\mu_t^2 := \text{Law}(X_t^{\mu_2})$. From (3) and Assumption 2.1, we have

$$\begin{aligned} \mathbb{E}|X_t^{\mu_1} - X_t^{\mu_2}| &\leq \mathbb{E}|X_0^{\mu_1} - X_0^{\mu_2}| + \mathbb{E} \int_0^t |b(X_s^{\mu_1}) - b(X_s^{\mu_2})| \, ds \\ &\quad + \int_0^t \int_{\mathbb{R}^d} |\mathbb{E} F(X_s^{\mu_1}, y) - \mathbb{E} F(X_s^{\mu_2}, y)| \text{Law}(X_s^{\mu_1})(dy) \, ds \\ &\quad + \int_0^t \left| \int_{\mathbb{R}^d} \mathbb{E} F(X_s^{\mu_2}, y) (\text{Law}(X_s^{\mu_1}) - \text{Law}(X_s^{\mu_2}))(dy) \right| ds. \end{aligned}$$

The functions F and b are Lipschitz, so there exists a constant L such that

$$\mathbb{E}|X_t^{\mu_1} - X_t^{\mu_2}| \leq \mathbb{E}|X_0^{\mu_1} - X_0^{\mu_2}| + L \int_0^t \mathbb{E}|X_s^{\mu_1} - X_s^{\mu_2}| \, ds.$$

By Grönwall's inequality, we deduce that

$$W_1(\text{Law}(X_t^{\mu_1}), \text{Law}(X_t^{\mu_2})) \leq \mathbb{E}|X_t^{\mu_1} - X_t^{\mu_2}| \leq e^{Lt} \mathbb{E}|X_0^{\mu_1} - X_0^{\mu_2}| = e^{Lt} W_1(\mu_1, \mu_2). \quad \square$$

2.6. Proof of Theorem 2.5

We now give the proof of Theorem 2.5. By combining Proposition 2.17, Corollary 2.16, and Proposition 2.6, we obtain:

Lemma 2.21. *Assume that $\lambda' > 0$, where λ' is given by (8). Let $\lambda \in (0, \lambda')$. There exists a constant C_λ such that for all $T > 0$, there is a constant C_T such that for all $v \in \mathcal{P}_1(\mathbb{R}^d)$ and for all $t \in [0, T]$:*

$$W_1(\text{Law}(X_t^v), v_\infty) \leq C_\lambda e^{-\lambda t} W_1(v, v_\infty) + C_T (W_1(v, v_\infty))^2.$$

Importantly, the constant C_λ above does not depend on T .

Proof. We write

$$\begin{aligned} W_1(\text{Law}(X_t^v), v_\infty) &= W_1(\text{Law}(Y_t^{\alpha+k^v, v}), v_\infty) \\ &\leq W_1(\text{Law}(Y_t^{\alpha+k^v, v}), \text{Law}(Y_t^{\alpha, v})) + W_1(\text{Law}(Y_t^{\alpha, v}), v_\infty) \\ &\leq C_* \int_0^t e^{-\kappa_*(t-\theta)} \|k_\theta^v\|_\infty d\theta + C_* W_1(v, v_\infty) e^{-\kappa_* t}. \end{aligned}$$

We used Corollary 2.16 to estimate $W_1(\text{Law}(Y_t^{\alpha+k^v, v}), \text{Law}(Y_t^{\alpha, v}))$ and (9) as well as Markov property to estimate $W_1(\text{Law}(Y_t^{\alpha, v}), v_\infty)$. Applying Proposition 2.17, we deduce that

$$\int_0^t e^{-\kappa_*(t-\theta)} \|k_\theta^v\|_\infty d\theta \leq \int_0^t e^{-\kappa_*(t-\theta)} \left[\|\varphi_\theta^v\|_\infty + \int_0^\theta \|\Omega_{\theta-u}(\varphi_u^v)\|_\infty du \right] d\theta + C_T (W_1(v, v_\infty))^2.$$

The estimate (10) implies that $\|\varphi_\theta^v\|_\infty \leq C_* W_1(v, v_\infty) \|\nabla_y F\|_\infty e^{-\kappa_* \theta}$. Fix $\lambda \in (0, \lambda')$. In view of (7), (12) and the proof of Proposition 2.6, the spectral assumption $\lambda' > 0$ implies that there exists a constant C such that

$$\forall h \in \mathcal{H}, \quad \|\Omega_t(h)\|_\infty \leq C e^{-\lambda t} \|h\|_{\mathcal{H}}.$$

Therefore, using that $\lambda < \kappa_*$, we have

$$\int_0^\theta \|\Omega_{\theta-u}(\varphi_u^v)\|_\infty du \leq C \int_0^\theta e^{-\lambda(\theta-u)} e^{-\kappa_* u} W_1(v, v_\infty) du \leq C_\lambda e^{-\lambda \theta} W_1(v, v_\infty).$$

Altogether, we deduce the stated inequality. $\square$

Finally, the proof of Theorem 2.5 is deduced from Lemma 2.21 by following the argument of [7, Proposition 5.2].

Proof of Theorem 2.5. We choose T large enough such that $C_\lambda e^{-\lambda T} \leq \frac{1}{4}$. We choose $\epsilon > 0$ small enough such that

$$W_1(v, v_\infty) \leq \epsilon \quad \implies \quad C_T (W_1(v, v_\infty))^2 \leq \frac{1}{4} W_1(v, v_\infty).$$

Therefore we have, by induction, provided that $W_1(v, v_\infty) \leq \epsilon$:

$$W_1(\text{Law}(X_{kT}^v), v_\infty) \leq (1/2)^k W_1(v, v_\infty).$$

We write $t = kT + s$ for some $s \in [0, T]$. Using Lemma 2.20, there exists a constant C such that

$$W_1(\text{Law}(X_t^v), v_\infty) \leq C (1/2)^k W_1(v, v_\infty) \leq \frac{C}{2} e^{-ct} W_1(v, v_\infty),$$

where $c := \frac{\log(2)}{T}$. This ends the proof of Theorem 2.5. $\square$

2.7. Connections with Lions derivatives

In this Section, we give a probabilistic interpretation of the linear maps $\Theta_t(h)$ and $\Omega_t(h)$. Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space. Let $Z_0, H \in L^2(\Omega, \mathcal{F}, \mathbb{P})$ such that $\text{Law}(Z_0) = \nu_\infty$. We denote by $h : \mathbb{R}^d \rightarrow \mathbb{R}^d$ a measurable function such that:

$$\mathbb{P}(\mathrm{d}\omega) \text{ p.s. } \mathbb{E}[H \mid Z_0] = h(Z_0).$$

It follows from $\mathbb{E}|H|^2 < \infty$ and from the Cauchy–Schwarz inequality that $h \in \mathcal{H}$. Define for all $x \in \mathbb{R}^d$, $t \geq 0$ and $\nu \in \mathcal{P}_2(\mathbb{R}^d)$:

$$\begin{aligned} u_t^x(\nu) &:= \mathbb{E}F(x, Y_t^{\alpha, \nu}), \\ v_t^x(\nu) &:= \mathbb{E}F(x, X_t^\nu). \end{aligned}$$

Proposition 2.22. *Under Assumptions 2.1 and 2.2, we have:*

1. *There exists a constant C_T such that for all random variables Z_0, H with $\text{Law}(Z_0) = \nu_\infty$ and $\mathbb{E}|H|^2 < \infty$, for all $t \in [0, T]$ and for all x we have, for $\nu = \text{Law}(Z_0 + H)$:*

$$|u_t^x(\nu) - \alpha(x) - \Theta_t(h)(x)| \leq C_T \mathbb{E}|H|^2.$$

2. *The function u_t^x is Lions differentiable at ν_∞ , with a derivative given by*

$$\partial_\nu u_t^x(\nu_\infty)(y) = \nabla_y \mathbb{E}_y F(x, Y_t^\alpha).$$

3. *There exists a constant C_T such that for all random variables Z_0, H with $\text{Law}(Z_0) = \nu_\infty$ and $\mathbb{E}|H|^2 < \infty$, for all $t \in [0, T]$ and for all x we have, for $\nu = \text{Law}(Z_0 + H)$:*

$$|v_t^x(\nu) - \alpha(x) - \Omega_t(h)(x)| \leq C_T \mathbb{E}|H|^2.$$

4. *The function v_t^x is Lions differentiable at ν_∞ , with a derivative given by*

$$(26) \quad \partial_\nu v_t^x(\nu_\infty)(y) = \nabla_y \mathbb{E}_y F(x, Y_t^\alpha) + \int_0^t \Omega_{t-s}(\nabla_y \mathbb{E}_y F(\cdot, Y_s^\alpha))(x) \mathrm{d}s.$$

Remark 2.23. In particular, from points 1 and 3, we have for all $h \in \mathcal{H}$:

$$\begin{aligned} \Theta_t(h)(x) &= \lim_{\epsilon \rightarrow 0} \frac{u_t^x(\text{Law}(Z_0 + \epsilon h(Z_0))) - \alpha(x)}{\epsilon}, \\ \Omega_t(h)(x) &= \lim_{\epsilon \rightarrow 0} \frac{v_t^x(\text{Law}(Z_0 + \epsilon h(Z_0))) - \alpha(x)}{\epsilon}. \end{aligned}$$

Proof. The first two points follow from the fact that $u_t^x(\nu)$ depends linearly on ν : $u_t^x(\nu) = \mathbb{E}g(Z_0 + H)$, with $g(y) := \mathbb{E}_y F(x, Y_t^\alpha)$. This function g is C^2 and there exists a constant C_T such that for all $t \in [0, T]$, for all $x \in \mathbb{R}^d$, $\|\nabla^2 g\|_\infty \leq C_T$. Therefore:

$$\begin{aligned} u_t^x(\nu) - \alpha(x) &= \mathbb{E}g(Z_0 + H) - \mathbb{E}g(Z_0) = \mathbb{E} \int_0^1 \nabla g(Z_0 + \theta H) \cdot H \mathrm{d}\theta \\ &= \mathbb{E} \nabla g(Z_0) \cdot H + \mathbb{E} \int_0^1 (\nabla g(Z_0 + \theta H) - \nabla g(Z_0)) \cdot H \mathrm{d}\theta \\ &= \mathbb{E} \nabla g(Z_0) \cdot H + O_T(\mathbb{E}|H|^2). \end{aligned}$$

So u_t^x is Lions differentiable at ν_∞ with $\partial_\nu u_t^x(\nu_\infty)(y) = \nabla g(y)$. In addition:

$$\mathbb{E} \nabla g(Z_0) \cdot H = \mathbb{E}[\nabla g(Z_0) \cdot \mathbb{E}(H \mid Z_0)] = \mathbb{E} \nabla g(Z_0) \cdot h(Z_0) = \Theta_t(h)(x).$$

The third point is a direct consequence of Proposition 2.17 and of the inequality:

$$W_1(\nu, \nu_\infty)^2 \leq W_2(\nu, \nu_\infty)^2 \leq \mathbb{E}|H|^2.$$

To check the last point, it suffices to show that

$$\mathbb{E}[\partial_v v_t^x(v_\infty)(Z_0) \cdot h(Z_0)] = \Omega_t(h),$$

where $\partial_v v_t^x(v_\infty)(y)$ is given by the right-hand side of (26). This equality follows by the linearity of $h \mapsto \Omega_t(h)$ and by Fubini's theorem. $\square$

2.8. Static bifurcation analysis: A Green–Kubo formula

Our result also provides some information on the number of invariant probability measures of (3). In this Section, in addition to Assumption 2.1, we assume that F is bounded

$$\sup_{x, y \in \mathbb{R}^d} |F(x, y)| < \infty,$$

and that the drift is confining in the sense that:

$$\exists R, \beta > 0, \quad |x - y| \geq R \implies (b(x) - b(y)) \cdot (x - y) \leq -\beta |x - y|^2.$$

We consider the following open ball of $\mathcal{K}$

$$\mathcal{K}_0 := \{\alpha \in \mathcal{K} : \|\alpha\|_{\mathcal{K}} \leq \|F\|_{\infty} + \|\nabla_x F\|_{\infty}\}.$$

Let $\alpha \in \mathcal{K}_0$. Then Assumption 2.2 holds with constants R, β independent of α . So the SDE (19) has a unique invariant probability measure, denoted by ν_∞^α . In addition, the bound (9) holds, for some constants C_* and κ_* which do not depend on α . We consider $\Psi : \mathcal{K}_0 \rightarrow \mathcal{K}_0$, defined by:

$$\forall \alpha \in \mathcal{K}_0, \quad \Psi(\alpha) := x \mapsto \int_{\mathbb{R}^d} F(x, y) \nu_\infty^\alpha(dy).$$

Note that there is a one-to-one correspondence between the invariant probability measures of (3) and the fixed-points of Ψ in $\mathcal{K}_0$. The following result is a generalization of the Green–Kubo formula [36, Ch. 5]:

Proposition 2.24. *The function Ψ is Frechet differentiable at every $\alpha \in \mathcal{K}_0$ and*

$$D_\alpha \Psi(\alpha) \cdot \epsilon = \int_0^\infty \Theta_t(\epsilon) dt = \hat{\Theta}(\epsilon)(0), \quad \epsilon, \alpha \in \mathcal{K}_0,$$

where Θ_t is given by (6).

Proof. We have for all $T \geq 0$,

$$\begin{aligned} \int_{\mathbb{R}^d} F(x, y) (\nu_\infty^{\alpha+\epsilon} - \nu_\infty^\alpha)(dy) &= [\mathbb{E}F(x, Y_T^{\alpha+\epsilon, \nu_\infty^{\alpha+\epsilon}}) - \mathbb{E}F(x, Y_T^{\alpha+\epsilon, \nu_\infty^\alpha})] \\ &\quad + [\mathbb{E}F(x, Y_T^{\alpha+\epsilon, \nu_\infty^\alpha}) - \mathbb{E}F(x, Y_T^{\alpha, \nu_\infty^\alpha})] \\ &=: A(x) + B(x). \end{aligned}$$

By (9), there exist positive constants C, κ_* such that $\|A\|_{\mathcal{K}} \leq C e^{-\kappa_* T} W_1(\nu_\infty^{\alpha+\epsilon}, \nu_\infty^\alpha)$: this term can be made arbitrarily small by choosing T sufficiently large. In addition, using Proposition 2.11, we have

$$B(x) = \int_0^T \int_{\mathbb{R}^d} [\nabla_y \mathbb{E}_y F(x, Y_{T-\theta}^\alpha) \cdot \epsilon(y)] \text{Law}(Y_\theta^{\alpha+\epsilon, \nu_\infty^\alpha})(dy) d\theta.$$

It follows that $\|B\|_{\mathcal{K}} \leq C \|\epsilon\|_{\infty}$. Letting $T \rightarrow \infty$ proves that Ψ is continuous. By refining the previous argument, we show that this function is Frechet differentiable with the stated derivative. Define $G_t^x(y) := \nabla_y \mathbb{E}_y F(x, Y_t^\alpha) \cdot \epsilon(y)$. We have $B(x) = \int_0^T \mathbb{E} G_{T-\theta}^x(Y_\theta^{\alpha+\epsilon, \nu_\infty^\alpha}) d\theta$ and, by Girsanov's theorem, provided that $\|\epsilon\|_{\infty}^2 T < 1$, we have:

$$\begin{aligned} |\mathbb{E} G_{T-\theta}^x(Y_\theta^{\alpha+\epsilon, \nu_\infty^\alpha}) - \mathbb{E} G_{T-\theta}^x(Y_\theta^{\alpha, \nu_\infty^\alpha})| &\leq C \|G_{T-\theta}^x\|_{\infty} \sqrt{\theta} \|\epsilon\|_{\infty} \\ &\leq C e^{-\kappa_*(T-\theta)} \|\epsilon\|_{\infty}^2 \sqrt{T}. \end{aligned}$$

Therefore, we deduce that

$$\left| B(x) - \int_0^\infty \int_{\mathbb{R}^d} \nabla_y \mathbb{E}_y F(x, Y_\theta^\alpha) \cdot \epsilon(y) v_\infty^\alpha(dy) d\theta \right| \leq C(\sqrt{T} \|\epsilon\|_\infty^2 + e^{-\kappa_* T}).$$

Overall, there exists a constant C such that

$$\begin{aligned} & \left| \int_{\mathbb{R}^d} F(x, y) (v_\infty^{\alpha+\epsilon} - v_\infty^\alpha)(dy) - \int_0^\infty \int_{\mathbb{R}^d} \nabla_y \mathbb{E}_y F(x, Y_\theta^\alpha) \cdot \epsilon(y) v_\infty^\alpha(dy) d\theta \right| \\ & \leq C[e^{-\kappa_* T} + \|\epsilon\|_\infty^2 \sqrt{T}]. \end{aligned}$$

We choose $T = 1/\|\epsilon\|_\infty$ and let $\|\epsilon\|_\infty$ goes to zero: the right-hand term is a $o(\|\epsilon\|_\infty)$. The same estimate holds on the derivative of Ψ with respect to x :

$$\begin{aligned} & \left| \int_{\mathbb{R}^d} \nabla_x F(x, y) (v_\infty^{\alpha+\epsilon} - v_\infty^\alpha)(dy) - \int_0^\infty \int_{\mathbb{R}^d} \nabla_y \mathbb{E}_y \nabla_x F(x, Y_\theta^\alpha) \cdot \epsilon(y) v_\infty^\alpha(dy) d\theta \right| \\ & \leq C[e^{-\kappa_* T} + \|\epsilon\|_\infty^2 \sqrt{T}]. \end{aligned}$$

Altogether, we deduce that $\alpha \mapsto \int_{\mathbb{R}^d} F(\cdot, y) v_\infty^\alpha(dy)$ is Frechet differentiable with the stated derivative. $\square$

The interpretation of this result is the following: static bifurcations, leading to a change of the number of invariant probability measures of (3), occur for parameters satisfying $\det(I - \hat{\Theta}(0)) = 0$. On the other hand, we expect Hopf bifurcations to occur at parameters for which $\det(I - \hat{\Theta}(i\omega)) = 0$, for some $\omega > 0$. Altogether, this covers the two canonical ways to break the stability condition $\lambda' > 0$, where λ' is given by (8). The study of these bifurcations is left to future research.

3. McKean–Vlasov of convolution type on the torus

Let $\beta > 0$. We consider the following McKean–Vlasov equation on the torus $\mathbb{T}^d := (\mathbb{R}/2\pi\mathbb{Z})^d$:

$$(27) \quad dX_t^\nu = - \int_{\mathbb{T}} \nabla W(X_t^\nu - y) \mu_t(dy) dt + \sqrt{2\beta^{-1}} dB_t \quad \text{with } \mu_t = \text{Law}(X_t^\nu)$$

with initial condition $\text{Law}(X_0^\nu) = \nu \in \mathcal{P}(\mathbb{T}^d)$. Here (B_t) is a Brownian motion on $\mathbb{T}^d$. This equation generalizes the Kuramoto model [1, 6, 28, 38], for which $d = 1$ and $W = -\kappa \cos$ for some constant $\kappa \geq 0$. We refer to [11] for a detailed presentation of examples that fit in the framework of (27), as well as a study of the static bifurcations of this equation. In this Section, we study the local stability of the uniform probability measure using the strategy and the tools introduced in Section 2.

3.1. Main result

Write the interaction kernel $W : \mathbb{T}^d \rightarrow \mathbb{R}$ in Fourier:

$$(28) \quad W(x) = \sum_{n \in \mathbb{Z}^d} \tilde{W}(n) e^{in \cdot x}, \quad x \in \mathbb{T}^d,$$

where $n \cdot x = \sum_{i=1}^d n_i x_i$. Let $|n|^2 = n \cdot n$. The Fourier coefficients of W are given by

$$\tilde{W}(n) = \frac{1}{(2\pi)^d} \int_{\mathbb{T}^d} W(y) e^{-in \cdot y} dy, \quad n \in \mathbb{Z}^d.$$

Assumption 3.1. Assume that $W \in C^3(\mathbb{T}^d)$ and that $\sum_{n \in \mathbb{Z}^d} |n|^2 |\tilde{W}(n)| < \infty$.

The uniform probability measure

$$U(dx) := \frac{dx}{(2\pi)^d}$$

is an invariant probability measure of (27) and

Theorem 3.2. *In addition to Assumption 3.1, assume that*

$$(29) \quad \lambda' := \inf_{n \in \mathbb{Z}^d \setminus \{0\}} |n|^2 (\beta^{-1} + \Re(\tilde{W}(n))) > 0.$$

Then $U(dx) = \frac{dx}{(2\pi)^d}$ is locally stable: there exists $\lambda \in (0, \lambda')$, $\epsilon > 0$ and $C > 1$ such that for all $\nu \in \mathcal{P}(\mathbb{T}^d)$ with $W_1(\nu, U) < \epsilon$, it holds that

$$\forall t \geq 0, \quad W_1(\text{Law}(X_t^\nu), U) \leq C W_1(\nu, U) e^{-\lambda t}.$$

Remark 3.3. The constant λ' is the exact analogue of (8) in Section 2. When the interaction kernel W is even, [11] studies the existence of bifurcations of the invariant probability measures of (27), provided that there exists $n \in \mathbb{Z}^d \setminus \{0\}$ such that $\beta^{-1} + \Re(\tilde{W}(n)) = 0$. Therefore, criterion (29) is sharp: we prove that the uniform measure is stable up to the first bifurcation. Note that we do not require here W to be even.

3.2. Proof

To simplify the notations, we first assume that $d = 1$. We discuss the case $d > 1$ afterward, most of the arguments being the same. We write $\sigma := \sqrt{2\beta^{-1}}$. The proof is divided into the following steps.

Step 1. Because ∇W is Lipschitz, the equation (27) has a unique path-wise solution satisfying the following apriori estimate:

$$\forall T > 0, \exists C_T : \forall \nu, \mu \in \mathcal{P}(\mathbb{T}), \quad \sup_{t \in [0, T]} W_1(\text{Law}(X_t^\nu), \text{Law}(X_t^\mu)) \leq C_T W_1(\nu, \mu).$$

Step 2. We define for $\nu \in \mathcal{P}(\mathbb{T})$, $x \in \mathbb{T}$ and $t \geq 0$:

$$k_t^\nu(x) := -\mathbb{E} \nabla W(x - X_t^\nu).$$

Recall that $U(dx) = \frac{dx}{2\pi}$. Because $k_t^U \equiv 0$, we have, by Step 1

$$\|k_t^\nu\|_\infty = \sup_{x \in \mathbb{T}} |k_t^\nu(x) - k_t^U(x)| \leq C_T \|\nabla^2 W\|_\infty W_1(\nu, U).$$

In addition, $x \mapsto k_t^\nu(x)$ is differentiable and

$$\|\nabla k_t^\nu\|_\infty = \sup_{x \in \mathbb{T}} |\nabla k_t^\nu(x) - \nabla k_t^U(x)| \leq C_T \|\nabla^3 W\|_\infty W_1(\nu, U).$$

Step 3. We now use that there exists $C_* > 1$ and $\kappa_* > 0$ such that

$$\forall x, y \in \mathbb{T}, \forall t \geq 0, \quad W_1(\text{Law}(x + \sigma B_t), \text{Law}(y + \sigma B_t)) \leq C_* e^{-\kappa_* t} |x - y|.$$

We refer to [35, Prop. 4]. We define for all $t \geq 0$, $x \in \mathbb{T}$ and $\nu \in \mathcal{P}(\mathbb{T})$:

$$\varphi_t^\nu(x) := -\mathbb{E} \nabla W(x - X_0^\nu - \sigma B_t),$$

where X_0^ν is independent of $(B_t)_{t \geq 0}$ and has law ν . Because $\|\nabla^2 W\|_\infty < \infty$, by the preceding result and the dual formulation of the W_1 norm, there exists a constant $C > 0$ such that:

$$\|\varphi_t^\nu\|_\infty \leq C e^{-\kappa_* t} W_1(\nu, U).$$

Step 4. Let $\mathcal{K} := W^{1,\infty}(\mathbb{T})$ be the space of bounded and Lipschitz continuous functions from $\mathbb{T}$ to $\mathbb{R}$. For $k \in C(\mathbb{R}_+; \mathcal{K})$ and $\nu \in \mathcal{P}(\mathbb{T})$, we consider $(Y_t^{k,\nu})$ the solution of the following linear non-homogeneous SDE

$$dY_t^{k,\nu} = k_t(Y_t^{k,\nu}) dt + \sigma dB_t,$$

starting with $\text{Law}(Y_0^{k,\nu}) = \nu$. Let $g \in C^2(\mathbb{T})$. The integrated sensibility formula of Proposition 2.11 is, in this context:

$$\mathbb{E} g(Y_t^{k,\nu}) - \mathbb{E} g(Y_t^{0,\nu}) = \int_0^t \int_{\mathbb{T}} \nabla_y \mathbb{E}_y g(y + \sigma B_{t-\theta}) \cdot k_\theta(y) \text{Law}(Y_\theta^{k,\nu})(dy) d\theta.$$

Step 5. We let for $h \in L^2(\mathbb{T})$ and $x \in \mathbb{T}$:

$$\Theta_t(h)(x) := - \int_{\mathbb{T}} \nabla_y \mathbb{E}_y \nabla W(x - y - \sigma B_t) \cdot h(y) \frac{dy}{2\pi}.$$

Using that $\mathbb{E}e^{i\sigma B_t} = e^{-\frac{n^2 \sigma^2}{2}t} = e^{-\frac{n^2 t}{\beta}}$, we find that the Fourier series of $\Theta_t(h)(x)$ is:

$$\Theta_t(h)(x) = - \sum_{n \in \mathbb{Z}} n^2 \tilde{W}(n) \tilde{h}(n) e^{-\frac{n^2 t}{\beta}} e^{inx}.$$

So Θ_t is diagonal in the Fourier basis $(e^{inx})_{n \in \mathbb{Z}}$ and $\widetilde{\Theta_t(h)}(n) = -n^2 \tilde{W}(n) e^{-\frac{n^2 t}{\beta}} \tilde{h}(n)$. In addition, using $|\tilde{h}(n)| \leq \|h\|_\infty$ we have:

$$\|\Theta_t(h)\|_\infty \leq C_0 e^{-t/\beta} \|h\|_\infty,$$

where $C_0 := \sum_{n \in \mathbb{Z}} n^2 |\tilde{W}(n)| < \infty$.

Step 6. We then define $\Omega_t(h)$ to be the unique solution of the Volterra integral equation:

$$\forall t \geq 0, \quad \Omega_t(h) = \Theta_t(h) + \int_0^t \Theta_{t-s}(\Omega_s(h)) ds.$$

Again, Ω_t is diagonal in the Fourier basis:

$$\Omega_t(h)(x) = - \sum_{n \in \mathbb{Z}} n^2 \tilde{W}(n) \exp(-n^2 t [\beta^{-1} + \tilde{W}(n)]) \tilde{h}(n) e^{inx}.$$

Let λ' be given by (29). We have:

$$\|\Omega_t(h)\|_\infty \leq C_0 e^{-\lambda' t} \|h\|_\infty.$$

So, under the condition $\lambda' > 0$, (Ω_t) decays at an exponential rate towards zero.

Step 7. Let $x \in \mathbb{T}$ be fixed. We now apply Step 4 with $g(y) := -\nabla W(x - y)$, and with $k_t(y) := k_t^v(y)$, where k_t^v is defined in Step 2. Note that with this choice, $Y_t^{k,v} = X_t^v$ and so $\mathbb{E}g(Y_t^{k,v}) = k_t^v(x)$. Similarly, $\mathbb{E}g(Y_t^{0,v}) = \varphi_t^v(x)$, where $\varphi_t^v(x)$ is defined in Step 3. Therefore, we have:

$$\begin{aligned} k_t^v(x) - \varphi_t^v(x) &= \int_0^t \int_{\mathbb{T}} \mathbb{E} \nabla^2 W(x - y - \sigma B_{t-\theta}) \cdot k_\theta^v(y) \text{Law}(X_\theta^v)(dy) d\theta \\ &= \int_0^t \Theta_{t-\theta}(k_\theta^v)(x) d\theta + R_t(x), \end{aligned}$$

where

$$\begin{aligned} R_t(x) &:= \int_0^t \mathbb{E}[G_{t,\theta}^x(X_\theta^v) - G_{t,\theta}^x(X_\theta^U)] d\theta, \\ G_{t,\theta}^x(y) &:= \mathbb{E} \nabla^2 W(x - y - \sigma B_{t-\theta}) \cdot k_\theta^v(y). \end{aligned}$$

Using the apriori estimates of Step 2, we deduce that there exists a constant C_T such that for all $0 \leq \theta \leq t \leq T$:

$$|\nabla_y G_{t,\theta}^x(y)| \leq C_T W_1(v, U).$$

Using Step 1, we conclude that $|R_t(x)| \leq C_T (W_1(v, U))^2$. To summarize, we have proven that for all $T > 0$, there exists a constant C_T such that for all $v \in \mathcal{P}(\mathbb{T})$ and for all $t \in [0, T]$:

$$\left| k_t^v(x) - \varphi_t^v(x) - \int_0^t \Theta_{t-\theta}(k_s^v)(x) d\theta \right| \leq C_T (W_1(v, U))^2.$$

Step 8. By iterating the last inequality of Step 7, we obtain that for all $T > 0$, there exists a constant C_T such that

$$\left| k_t^v(x) - \varphi_t^v(x) - \int_0^t \Omega_{t-\theta}(\varphi_s^v)(x) d\theta \right| \leq C_T (W_1(v, U))^2.$$

Step 9. We prove that there exists a constant $C > 0$ such that for all $t > 0$, for all $k \in C([0, t]; \mathcal{K})$ and for all $v \in \mathcal{P}(\mathbb{T})$, it holds that

$$W_1(\text{Law}(Y_t^{k,v}), \text{Law}(Y_t^{0,v})) \leq C \int_0^t e^{-\kappa_*(t-\theta)} \|k_\theta\|_\infty d\theta.$$

The proof is obtained exactly as in Corollary 2.16; it uses the estimates of Step 3.

Step 10. We fix $\lambda \in (0, \min(\kappa_*, \lambda'))$. Using Step 8, Step 6, and Step 3, we deduce that there exists $C_\lambda > 0$ such that for all $T > 0$, there is a constant C_T such that for all $t \in [0, T]$ and $v \in \mathcal{P}(\mathbb{T})$:

$$\|k_t^v\|_\infty \leq C_T (W_1(v, U))^2 + C_\lambda W_1(v, U) e^{-\lambda t}.$$

Let $k_t(x) := k_t^v(x)$. Using that $X_t^v = Y_t^{k,v}$, we have:

$$W_1(\text{Law}(X_t^v), U) \leq W_1(\text{Law}(Y_t^{k,v}), \text{Law}(Y_t^{0,v})) + W_1(\text{Law}(Y_t^{0,v}), U).$$

By Step 3, we have

$$W_1(\text{Law}(Y_t^{0,v}), U) \leq C_* e^{-\kappa_* t} W_1(v, U).$$

By Step 9, we have

$$W_1(\text{Law}(Y_t^{k,v}), \text{Law}(Y_t^{0,v})) \leq C \int_0^t e^{-\kappa_*(t-\theta)} \|k_\theta^v\|_\infty d\theta.$$

Altogether, we deduce that there is a constant C_λ such that for all $T > 0$, there exists $C_T > 0$ such that for all $t \in [0, T]$, for all $v \in \mathcal{P}(\mathbb{T})$, we have:

$$W_1(\text{Law}(X_t^v), U) \leq C_\lambda W_1(v, U) e^{-\lambda t} + C_T (W_1(v, U))^2.$$

The proof of Theorem 3.2 is deduced from this estimate, exactly as we did at the end of Section 2.6. This ends the proof for $d = 1$.

The case $d > 1$ is similar; the only differences are in the expressions of Θ_t and Ω_t of Steps 5 and 6. Given $n \in \mathbb{Z}^d$, we denote by $P_{(n)}$ the $d \times d$ matrix defined by $P_{(n)} = (n_i n_j)_{1 \leq i, j \leq d}$. We find that for all $h \in L^2(\mathbb{T}^d; \mathbb{R}^d)$ and for all $x \in \mathbb{T}^d$,

$$\Theta_t(h)(x) = - \sum_{n \in \mathbb{Z}^d} e^{in \cdot x} \tilde{W}(n) e^{-\frac{|n|^2 t}{\beta}} P_{(n)} \tilde{h}(n),$$

and

$$\Omega_t(h)(x) = - \sum_{n \in \mathbb{Z}^d} e^{in \cdot x} \tilde{W}(n) e^{-\frac{|n|^2 t}{\beta}} P_{(n)} e^{-t \tilde{W}(n) P_{(n)}} \tilde{h}(n).$$

The eigenvalues of $P_{(n)}$ are $|n|^2$ (of order 1) and zero (of order $d - 1$). In addition, it holds that for $\theta \in \mathbb{R}$,

$$(e^{\theta P_{(n)}})_{i,j} = \delta_{\{i=j\}} + \frac{n_i n_j}{|n|^2} (e^{\theta |n|^2} - 1).$$

Therefore, the estimates of Steps 5 and 6 still hold in dimension $d > 1$. This ends the proof.

Appendix

Proof of Lemma 2.9

Recall that $\mathcal{V}(x, y) := b(x) + F(x, y)$. When $\sigma \equiv 0$, then $v_\infty = \delta_{x_*}$ for some $x_* \in \mathbb{R}^d$. Therefore (6) writes:

$$\Theta_t(h)(x) = \nabla_y \mathcal{V}(x, x_*) e^{t \nabla_x \mathcal{V}(x_*, x_*)} \cdot h(x_*) =: A_t^x \cdot h(x_*).$$

We look at solutions of (12) of the form: $\Omega_t(h)(x) := B_t^x \cdot h(x_*)$, for some matrices B_t^x . We find that B_t^x satisfies

$$(30) \quad \forall t \geq 0, \quad B_t^x = A_t^x + \int_0^t A_{t-s}^x \cdot B_s^{x_*} ds.$$

We first study this equation for $x = x_*$. For all $z \in \mathbb{C}$ with $\Re(z) > -\kappa$,

$$\widehat{A^{x_*}}(z) = \nabla_y \mathcal{V}(x_*, x_*) \int_0^\infty e^{-t(zI_d - \nabla_x \mathcal{V}(x_*, x_*))} dt = \nabla_y \mathcal{V}(x_*, x_*) (zI_d - \nabla_x \mathcal{V}(x_*, x_*))^{-1}.$$

Lemma A.1. *Let $z \in \mathbb{C}$ such that $\Re(z) > -\kappa$. Then $\det(I_d - \widehat{A^{x_*}}(z)) = 0$ if and only if z is an eigenvalue of $\nabla_x \mathcal{V}(x_*, x_*) + \nabla_y \mathcal{V}(x_*, x_*)$.*

Proof. When $\det(I_d - \widehat{A^{x_*}}(z)) = 0$, there exists $u \in \mathbb{R}^d \setminus \{0\}$ such that

$$u = \nabla_y \mathcal{V}(x_*, x_*) (zI_d - \nabla_x \mathcal{V}(x_*, x_*))^{-1} u.$$

Setting $v = (zI_d - \nabla_x \mathcal{V}(x_*, x_*))^{-1} u$, we have $v \neq 0$ and

$$zv = (\nabla_x \mathcal{V}(x_*, x_*) + \nabla_y \mathcal{V}(x_*, x_*))v.$$

So z is an eigenvalue of $\nabla_x \mathcal{V}(x_*, x_*) + \nabla_y \mathcal{V}(x_*, x_*)$. The converse statement is proved similarly. $\square$

Now, assume that all the real parts of the eigenvalues of $\nabla_x \mathcal{V}(x_*, x_*) + \nabla_y \mathcal{V}(x_*, x_*)$ are less than $-\lambda'$, for some $\lambda' \in (0, \kappa)$. Then, for all $\Re(z) \geq -\lambda'$, $\det(I - A_t^{x_*}) \neq 0$. Applying [30, Th. 4.1], we deduce that $\int_0^\infty e^{\lambda' t} \|B_t^{x_*}\| dt < \infty$. Using (30), one deduces that $\|B_t^{x_*}\| e^{\lambda' t} < \infty$, and so

$$\|\Omega_t(h)\|_{\mathcal{H}} = |\Omega_t(h)(x_*)| = |B_t^{x_*} \cdot h(x_*)| \leq C e^{-\lambda' t} |h(x_*)| = C e^{-\lambda' t} \|h\|_{\mathcal{H}}.$$

Therefore, $\lambda' > 0$. Conversely, if $\lambda' > 0$ where λ' is given by (8) holds, then for $\Re(z) > -\lambda'$, $\det(I_d - \widehat{A^{x_*}}(z)) \neq 0$. So by Lemma A.1, z is not an eigenvalue of $\nabla_x \mathcal{V}(x_*, x_*) + \nabla_y \mathcal{V}(x_*, x_*)$. We deduce that all the eigenvalues of this matrix have real parts less or equal to $-\lambda'$.

Proof of Proposition 2.10

Denote by $\bar{\Theta}_t := \Theta_t^\sigma - \Theta_t^0$ and let $L_t(h) := \bar{\Theta}_t(h) + \int_0^t \Omega_{t-s}^0(\bar{\Theta}_s(h)) ds$. We also let R be the resolvent of L , such that R solves

$$R_t = L_t + \int_0^t L_{t-s} \cdot R_s ds.$$

Lemma A.2. *It holds that for all $t \geq 0$, $\Omega_t^\sigma = \Omega_t^0 + R_t + \int_0^t R_{t-s} \cdot \Omega_s^0 ds$.*

Proof. Let $Q_t := \Omega_t^0 + R_t + \int_0^t R_{t-s} \cdot \Omega_s^0 ds$. To simplify the notation, we write for $A, B \in \mathcal{L}(\mathcal{H})$:

$$(A * B)_t = \int_0^t A_{t-s} \cdot B_s ds.$$

We have $L * Q = L * \Omega^0 + L * R + (L * R * \Omega^0) = R * \Omega^0 + L * R$. Therefore, using that $L * R = R - L$ and the definition of Q , we find that Q solves

$$(31) \quad Q = \Omega^0 + L + L * Q.$$

As $L = \bar{\Theta} + \Omega^0 * \bar{\Theta}$, we have

$$Q - (\bar{\Theta} + \Omega^0 * \bar{\Theta}) * Q = \Omega^0 + \bar{\Theta} + \Omega^0 * \bar{\Theta}.$$

We multiply on the left by Θ^0 . Using that $\Theta^0 * \Omega^0 = \Omega^0 - \Theta^0$, we find that

$$\Theta^0 * Q - \Omega^0 * \bar{\Theta} * Q = \Omega^0 - \Theta^0 + \Omega^0 * \bar{\Theta}.$$

Finally, using that $\bar{\Theta} = \Theta^\sigma - \Theta^0$, we find that $\Theta^0 - \Omega^0 * \bar{\Theta} * Q = \Omega^0 * \Theta^\sigma$. Altogether:

$$L * Q = \Theta^\sigma * Q - \Omega^0 * \Theta^\sigma.$$

We substitute this equality in (31) to finally obtain that

$$Q = \Theta^\sigma + \Theta^\sigma * Q.$$

As Ω^σ is the unique solution of this Volterra integral equation, we deduce that $\Omega^\sigma = Q$ as claimed. $\square$

By Assumptions, there exists $\sigma_0, \kappa > 0$ small enough such that for all $\sigma \in M_d(\mathbb{R})$ with $\det(\sigma) > 0$ and $\|\sigma\|_2 \leq \sigma_0$, we have

$$\sup_{t \geq 0} e^{\kappa t} \|L_t\|_{\mathcal{L}(\mathcal{H})} \leq \frac{\kappa}{4}.$$

Therefore, we deduce that $\sup_{t \geq 0} e^{\frac{\kappa}{2}t} \|R_t\|_{\mathcal{L}(\mathcal{H})} \leq \frac{\kappa}{2}$ and so the stated result follows using Lemma A.2.

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